

TEAM ORANGE



**Atmospheric Drag,
Occultation 'N' Ionospheric
Scintillation Mission**

Summer School Alpbach 2013

**Space Weather:
Science, Missions and Systems**

July 16-25, Alpbach/Tyrol, Austria

Outline

- **Mission Statement & Objectives**
- **Mission Requirements**
- **Instrumentation**
- **Orbit**
- **Space Segment**
- **Ground Segment & Operations**
- **Development, Cost & Risks**
- **Disposal**
- **Summary**



Mission Statement & Objectives

Mission Statement & Objectives

Mission Statement



The mission goal is to study the **dynamics of the thermosphere and ionosphere** over a **full solar cycle (i.e. 11 years)** in LEO.

Mission objectives

- Build a model for **satellite drag** in relation to Space WEather (SWE).
- Provide data to improve **ionospheric models**.
- Provide **near real-time Total Electron Content (TEC) data** in the northern polar region.
- Contribute to models for **radio communication perturbation** in relation to SWE.
- Operate for a **full solar cycle (11 years)** to gather significantly improved statistics.

Problem Statement

Why are thermosphere and ionosphere important?

= the atmospheric layer where we experience space weather (= SWE)

Incomplete understanding of Solar activity and SWE effects on the terrestrial thermosphere and ionosphere

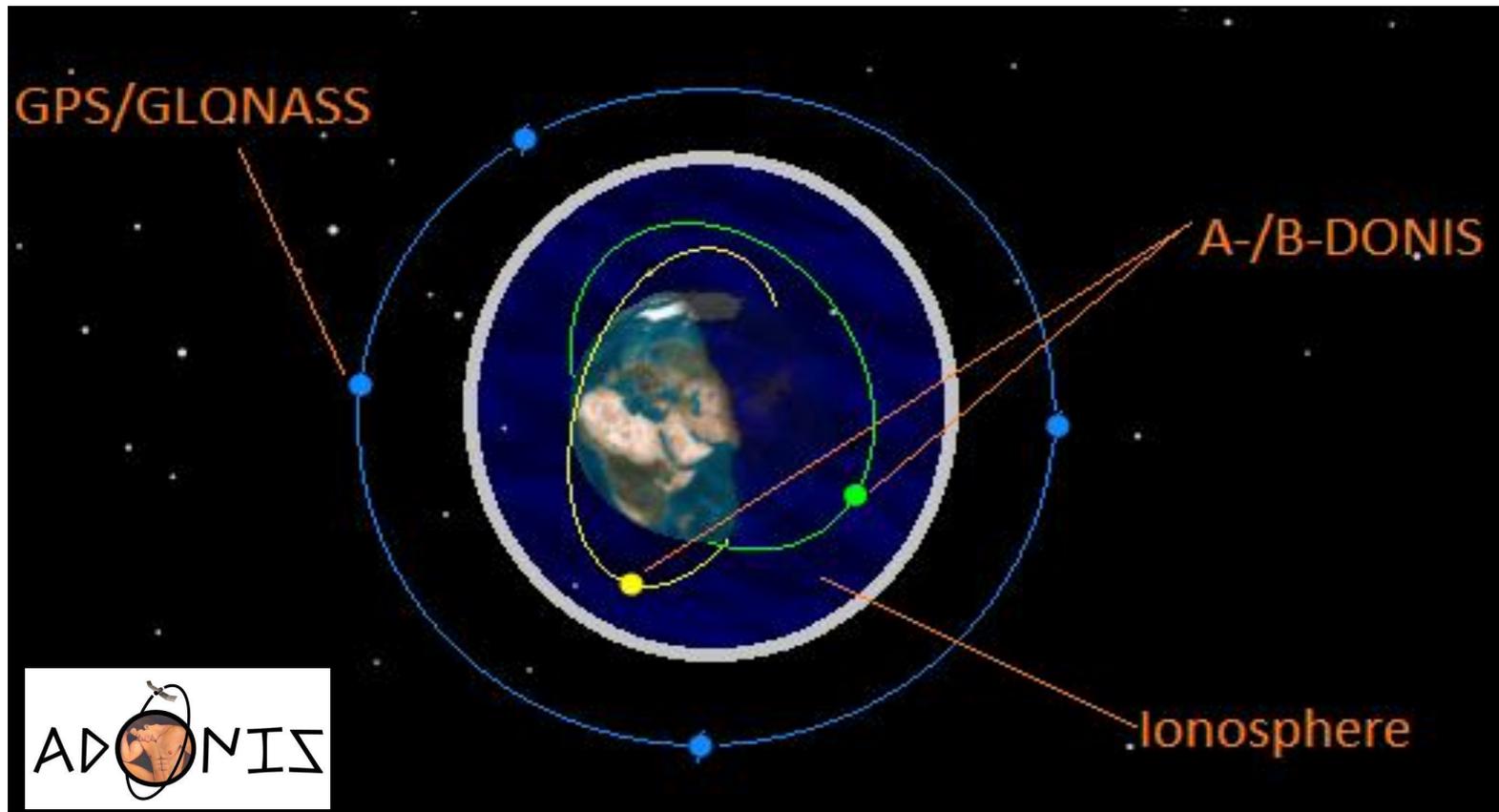
Ionospheric space weather causes:

1. **Satellite drag**: better description needed for launch planning, prediction of uncontrolled re-entries, control of LEO s/c
2. **Disturbances** related to variations in Total Electron Content (TEC):
 - a. in critical **HF communications** during polar flights, emergency relief, military operations
 - b. in **GNSS signals**
 - c. in **satellite telecommunication and broadcasting**
→ **Safety, commercial and strategic impacts**



Source: Wordpress

Overview of the ADONIS Mission



Ionosphere	GPS	GLONASS	A-/B-DONIS	LEO
100 - 1000 km	20 200 km	19 100 km	300 - 800 km	160 - 2000 km

Mission Science Goal I

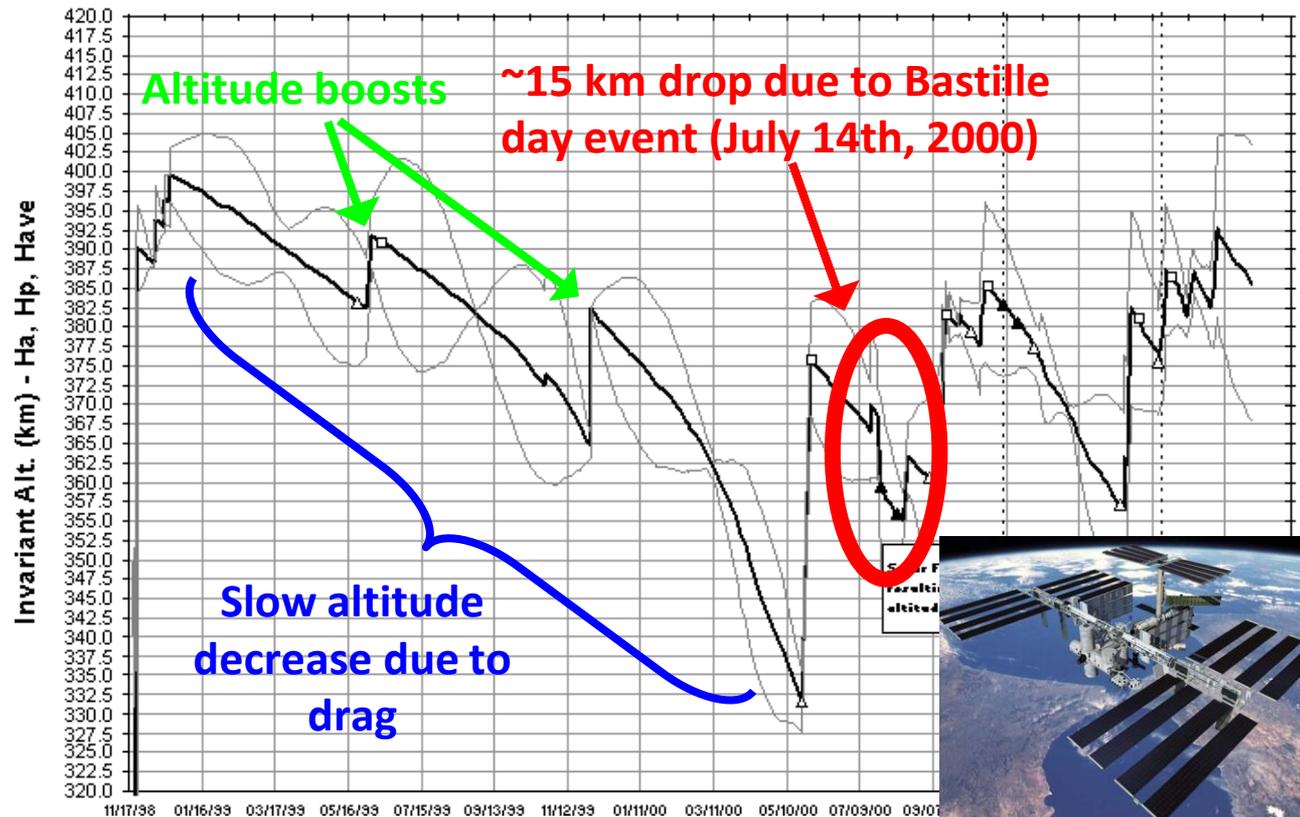
Improve the quality and reliability of current **satellite drag models** by measuring in-situ both the drag and the parameters relevant to model it.

International Space Station As Flown Altitude Profile

(Based on MCC-M/USSP Tracked SV Data)

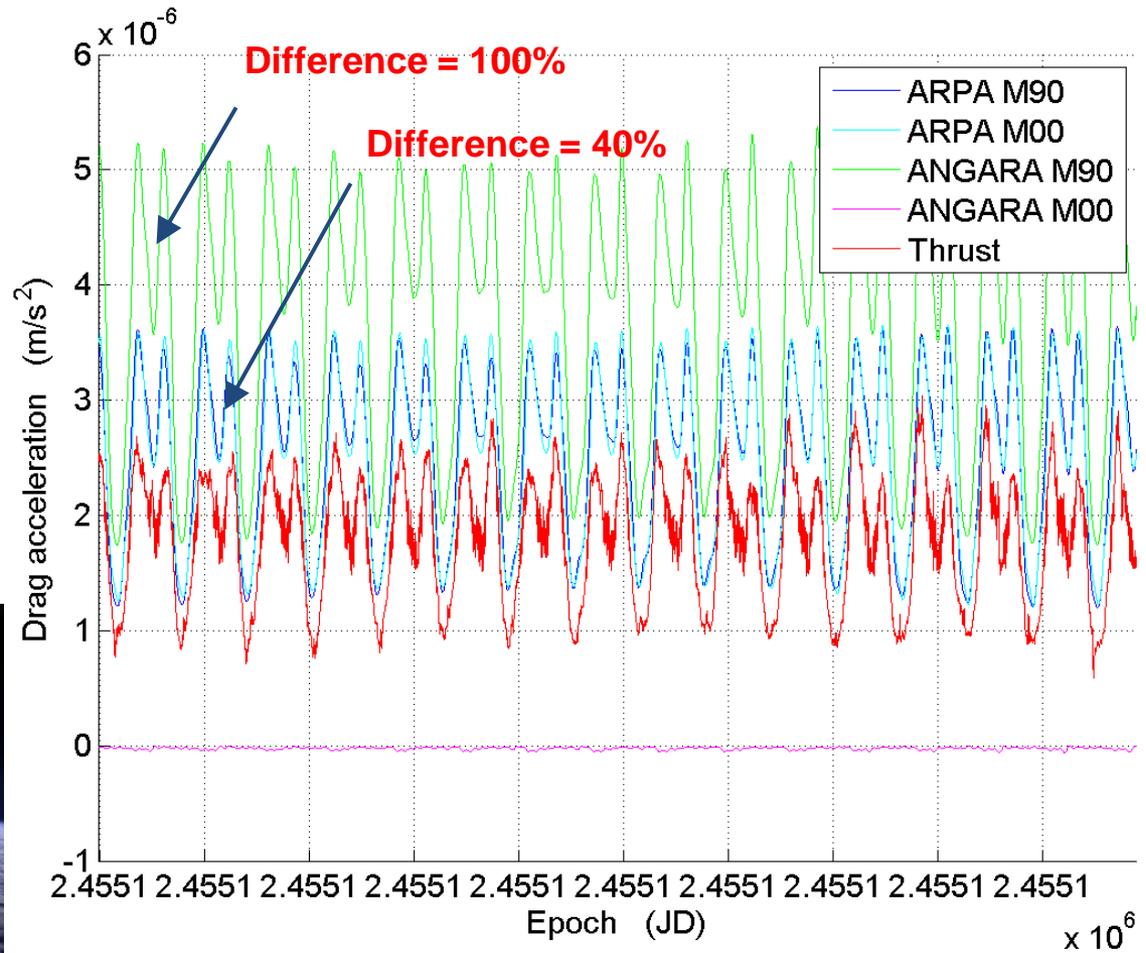
- ISS altitude from 11/1998 to 5/2001
- Drag causes constant dropping of altitude
- Altitude boosts needed
- Note drop due to Bastille day event

Source: Chammons 2001



Mission Science Goal I

- GOCE thrust compared to drag modelling
- Thrust is compensating directly the drag
- Note the difference between accelerations computed and observed



Source: F. Gini, 2013

Mission Science Goal I

Necessary parameters for derivation of the drag:

$$a = \frac{\rho A v^2}{2m} c_d(T_0, T_S, m_p, n_p)$$

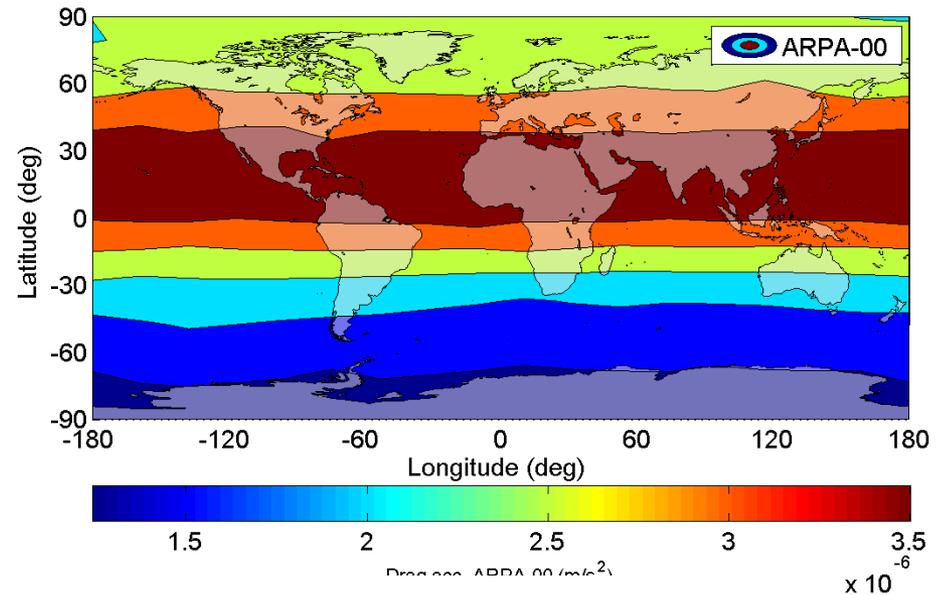
T_0 : atmospheric temperature

m_p : average mass of the particles

n_p : particle density

ρ : atmospheric density

v : velocity of the satellite with respect to the atmosphere



a : drag acceleration

A : cross sectional area

m : mass of the satellite

c_d : drag coefficient

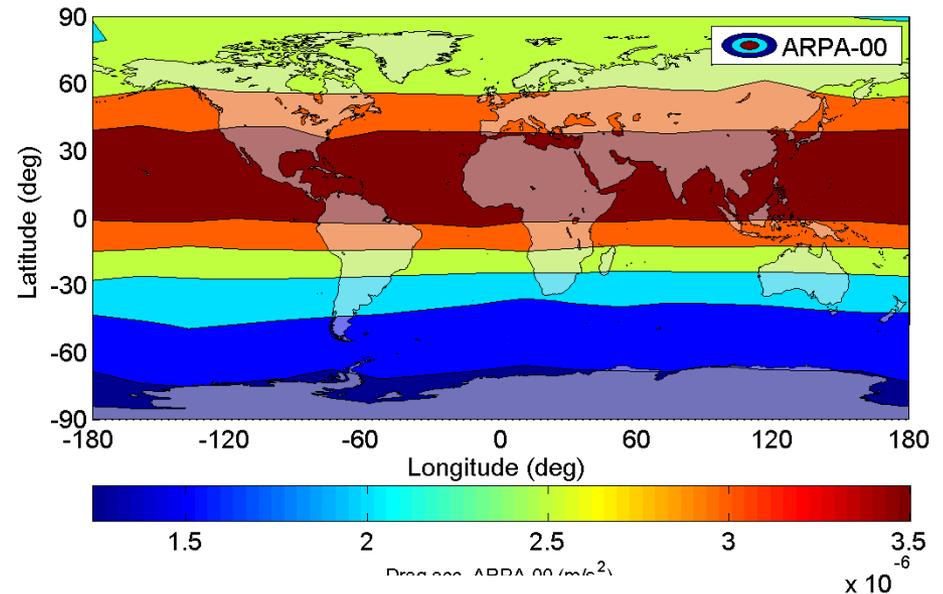
T_S : spacecraft temperature

Mission Science Goal I

Necessary parameters for derivation of the drag:

$$a = \frac{\rho A v^2}{2m} c_d(T_0, T_S, m_p, n_p)$$

- T_0 : atmospheric temperature
- m_p : average mass of the particles
- n_p : particle density
- ρ : atmospheric density
- v : velocity of the satellite with respect to the atmosphere



- a : drag acceleration
- A : cross sectional area
- m : mass of the satellite
- c_d : drag coefficient
- T_S : spacecraft temperature

Instruments: Spectrometer, Thermistor, Accelerometer, Langmuir Probe, Particle Analyser

Mission Benefits I

Related missions: GOCE, QB50

Benefits



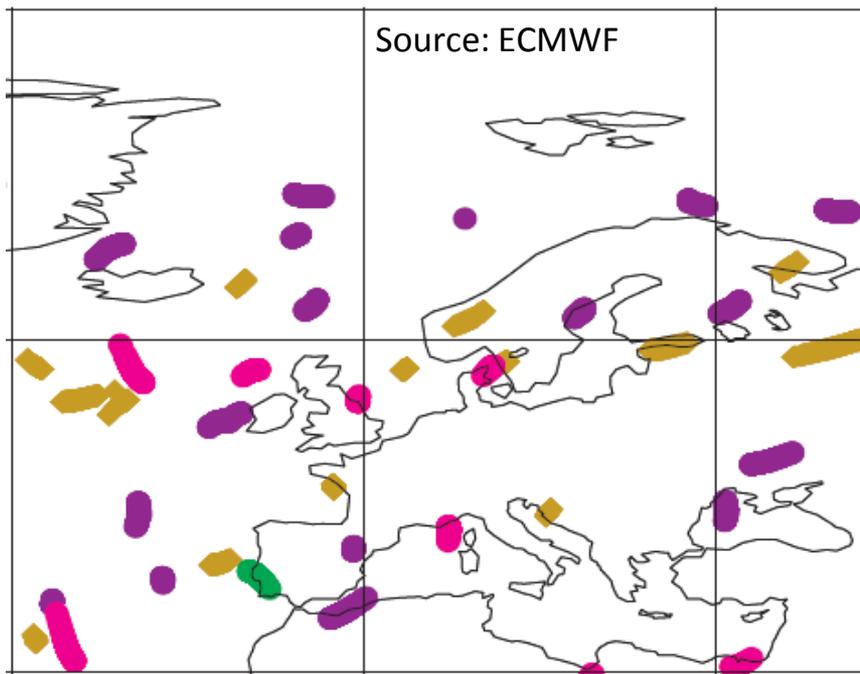
- **Observe different altitude and wider altitude range** than GOCE
- Measure all the parameters important for **drag in-situ**
- **Connect SWE** with drag
- Orbit design allows the study of **daily to seasonal variations**
- Long duration: large statistics for different SWE
- Continue the drag **measurements during de-orbiting** and end of mission

Mission Science Goal II

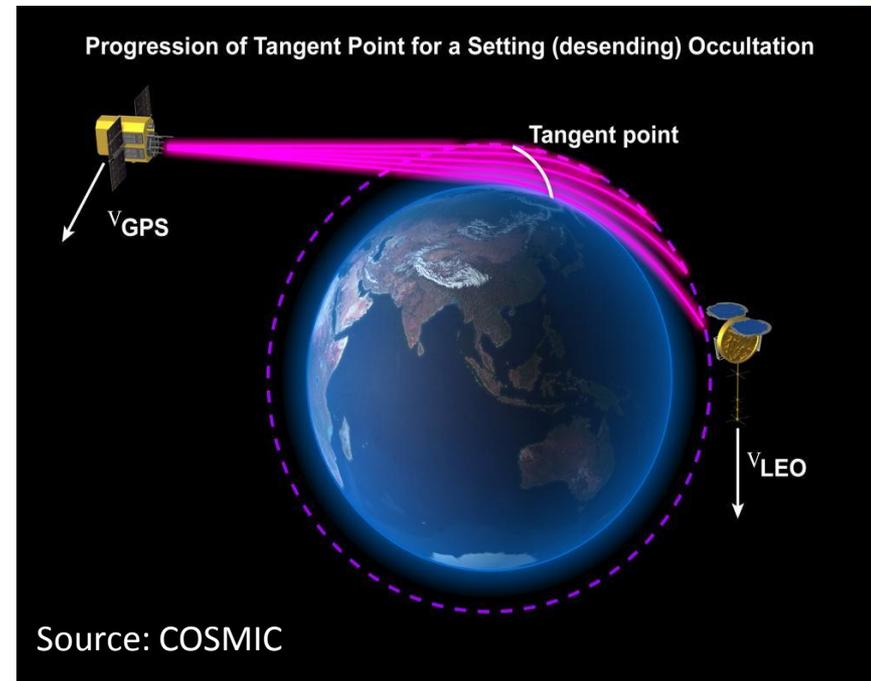
Provide additional Total Electron Content (TEC) data for ionospheric monitoring.

Radio occultation (RO)

- Doppler shift of **GNSS signal** measured on LEO polar S/C provides more **high-resolution vertical** profiles of the electron density above 80 km of **regions with sparse coverage**.
- **Near Real Time (NRT) monitoring of Arctic region** (NRT downlink to Svalbard GS)



Geograph. coverage of 6 h RO data over Europe – ROM SAF

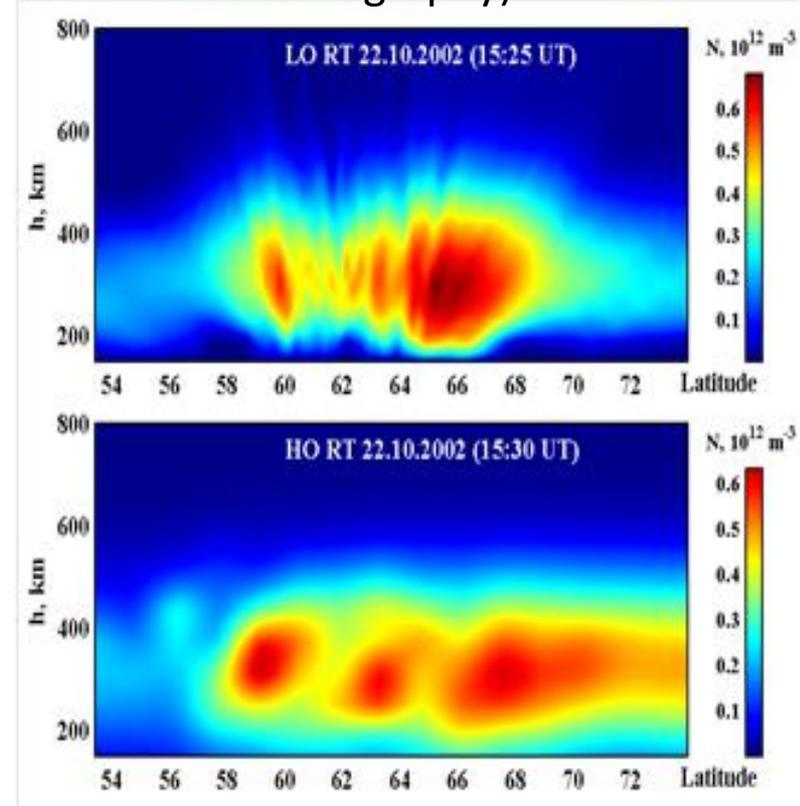
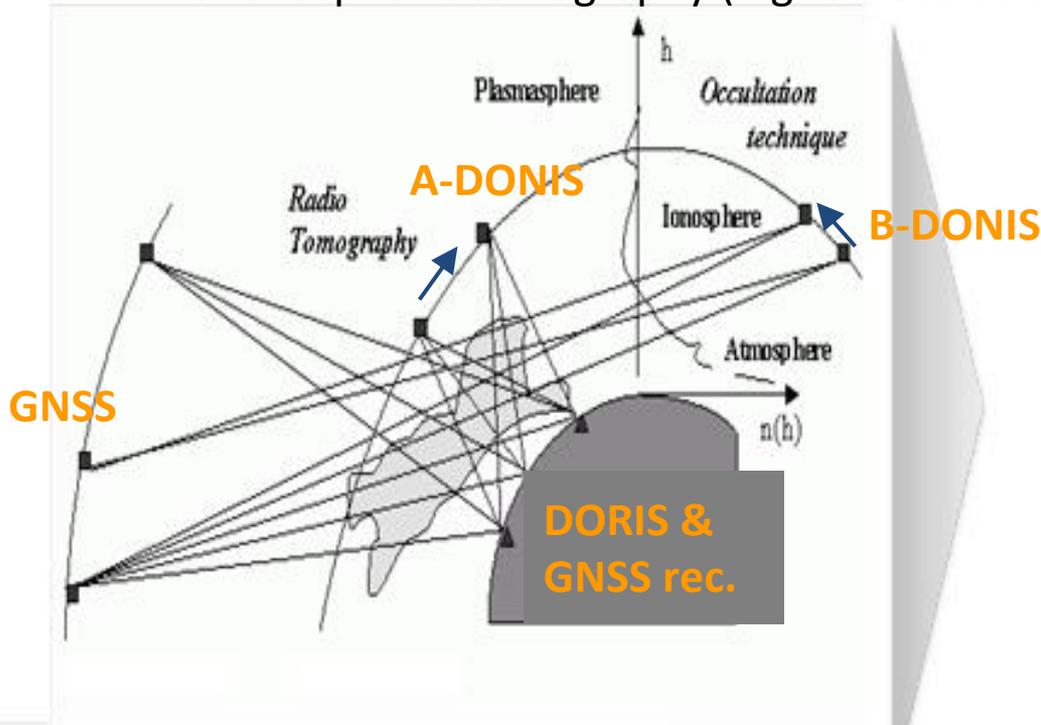


GNSS Radio Occultation principle

Mission Science Goal II

Ionospheric tomography with scintillation and occultation combined

- Scintillation from **10 LEO S/C** and **56 DORIS GS beacons** (global: lat. 70°S – 80°N) interpreting ionospheric irregularities ranging from a few up to hundreds of meters
- LEO ionospheric tomography (higher resolution than GNSS tomography)

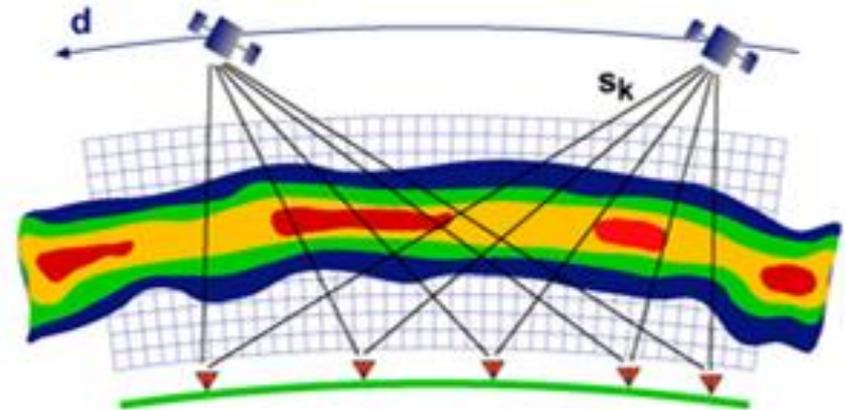


RT and OT

Source: Rekenhaller et al., 2013

Mission Benefits II

Related missions: COSMIC, CHAMP



Benefits:

- The **only available** TEC with scintillation from orbital **S/C - S/C links**:
in average 20 contacts per day per S/C (20–40 min each, up to 200 Hz)
- Scintillation from 56 DORIS ground stations **no S/C currently provides**
- Hi-res LEO tomog., use **high ratio of frequencies**: 5.1, 2.6 (GPS use 1.3)
- 1k occultations per day in average (250 events per S/C per GNSS system)
- **3D** global TEC maps, **NRT data in the arctic region**

Mission Requirements

Mission Requirements

M.1.	Perform measurements related to S/C drag coefficient at LEO
M.2.	Ionospheric tomography from LEO based on radio occultation and scintillation
O.1.	Obtained results shall be delivered to scientific community
O.2.	Obtained occultation results shall enable provision of near real-time service
O.3.	Duration of mission shall cover one full solar cycle (i.e. 11 yrs)
O.4.	The S/C shall keep the same cross area normal to the velocity vector
D.1.	S/C shall fit into Vega fairing
D.2.	On-board components shall not interfere with each other
D.3.	S/C shall provide on-board payload instruments to meet the mission objectives
D.4.	GS shall provide uplink and downlink capability
P.1.	The acceleration shall be determined at least once per second

M: Mission goal; O: Operational req; D: Design req; P: Performance req.

Science Requirements

Requirements	Range/Sensitivity	Instrument
Particle composition	0–50 amu, 128 bins, 1 Hz NRT	Ion & Neutral Mass Spectrometer (INMS)
On-board temperature	1°C accuracy, 1 Hz	Thermistors
S/C acceleration	10^{-8} m/s ² , 1 Hz	Italian Spring Accelerometer (ISA)
Plasma velocity, temp.	10 eV–30 keV, 1 Hz NRT	3D Particle Analyser (3DPA)
Plasma density	10^9 – 10^{12} /m ³ , 1 Hz NRT	Langmuir Probe (m-NLP)
TEC from RO	1k RO events, 0.001 TECU rel. (3 TECU abs.), 10Hz	Radio occultation instr. (IGOR+)
Ionospheric scintillation	0.003 TECU rel. (1 TECU abs.) 10Hz S4	Radio tomography receiver (CITRIS)
Magnetic field	+/-80 μ T, 0.5 nT, 0.1 Hz NRT	Flux Gate Magnetometer (FGM)

Drag

Ionospheric/thermospheric dynamics

Both

All TRL 9 except 3DPA
(will fly in Dec. 2013)

Instrumentation

Payload: Occultation and Scintillation

IGOR+ radio occultation instrument:

- RO of 2 GNSS (GPS, GLONASS)
- 5 kg, 22 W, 21.8×24.0×14.4 cm³
- Flight heritage, modified for KOMPSAT-5 (2013)
Tri-G (+ GALILEO) TBC follow-up mission (50 W req.)



CITRIS ionospheric tomography instrument:

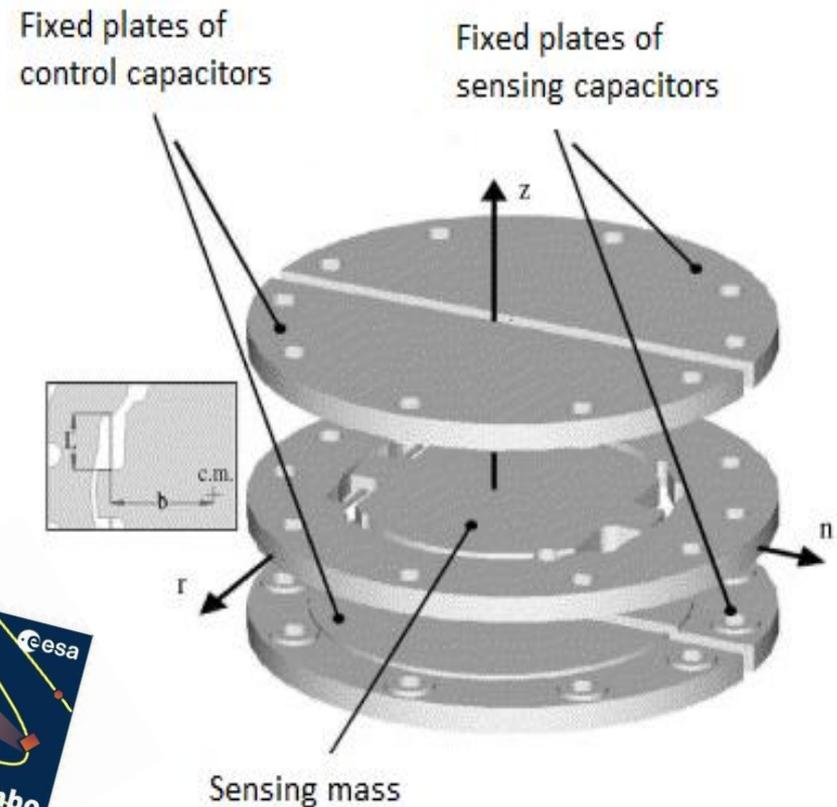
- Reconstruction of scintillation parameters
- Receiving 56 DORIS GS @ 401, 2036 MHz
- 10 satellite transmitter – sat. receiver links @150, 400, and 1067 MHz
- Sampling up to 200 Hz
- 4.5 kg, 12.3 W, 40.0×31.0×12.0 cm³
- Flown on STPSAT1 (3/2007 – 10/2009)



Both only receivers, no RF interference with plasma instrument suite

Italian Spring Accelerometer (ISA)

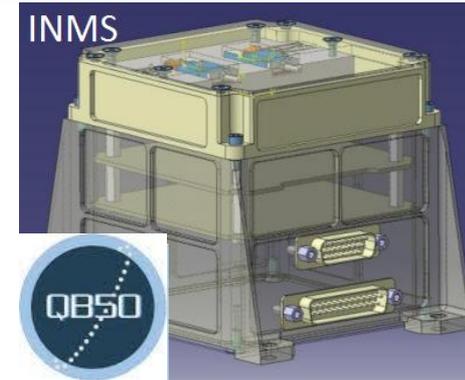
- Planned for BepiColombo
- **Full acceleration vector** of the satellite
- Sensitivity of $\sim 10^{-8} \text{ m/s}^2$
- Modification needed in order to measure at higher frequencies (at 1 Hz)



Payload: INMS, 3DPA, m-NLP, FGM

Ion and Neutral Mass Spectrometer (INMS)

- Resolves ions 0.1 - 28 eV and neutrals O, O₂, N₂
- QB50 planned



3D Particle Analyser (3DPA)

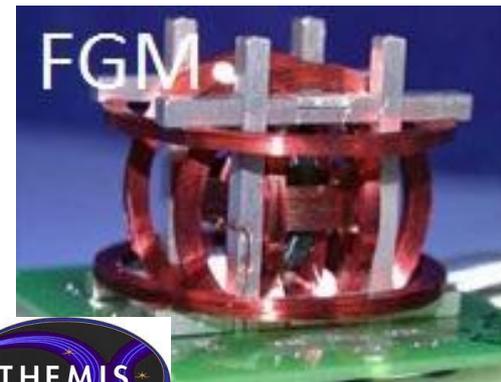
- Resolves ions and electrons few eV–30 keV
- Two detectors on top and bottom of satellite
- Test flight on sounding rocket mission ICI-4, Dec. 2013

Multi-Needle Langmuir Probe (m-NLP)

- 0.6 m booms, 3 probes
- Flown on CubeSTAR, QB50 planned

Flux Gate Magnetometer (FGM)

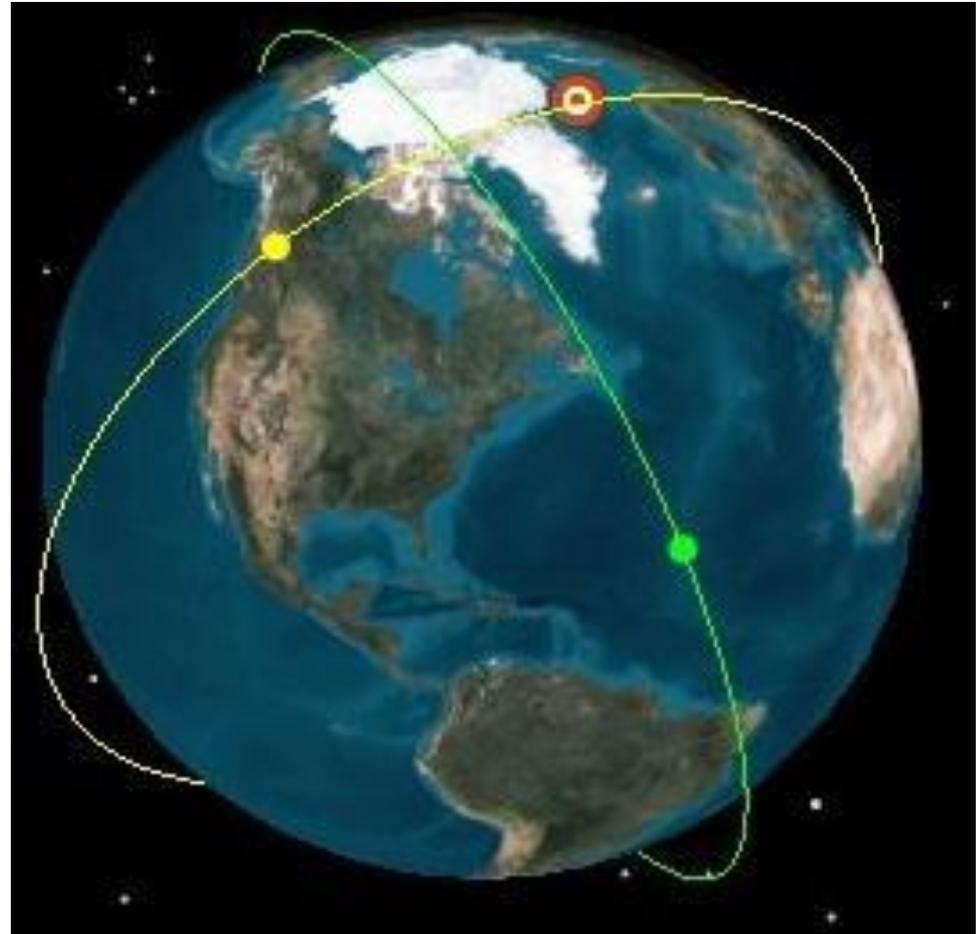
- +/-80 μ T, resolution 0.5 nT
- Boom-mounted (1 m in front)
- Flown on Cluster, THEMIS, etc.



Orbit

Final constellation:

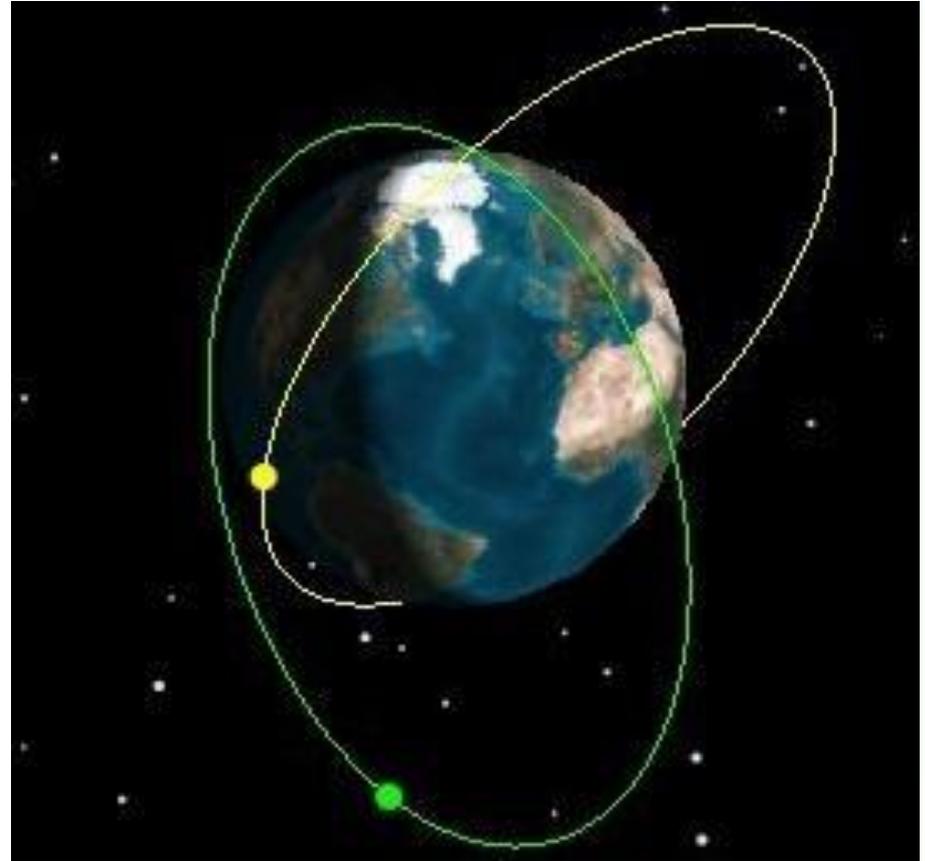
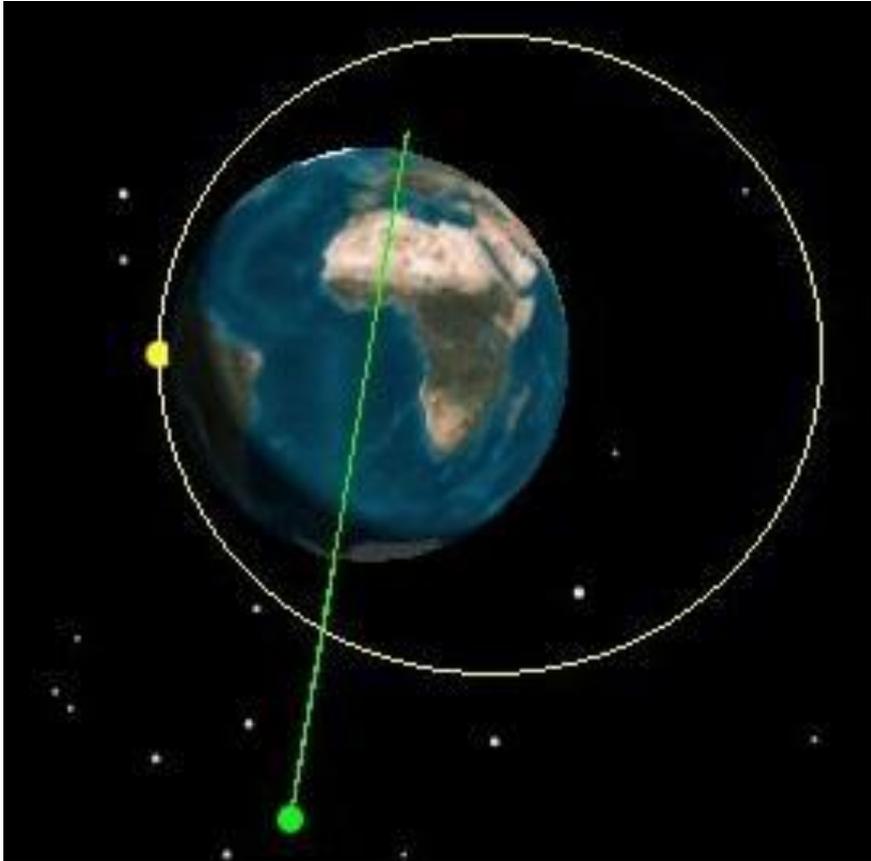
- **2 elliptical orbits** with apogee altitude 800 km, perigee altitude 300 km and **80° inclination**.
- **90° difference** in the plane of the two orbits (Right Ascension of the Ascending Node – RAAN) and 90° difference in argument of perigee.



→ Space and time resolution,
different local times at passage.



Amplified View



Perigee Determination

$$a = \frac{\rho A v^2}{2m} c_d(T_0, T_S, m_p, n_p)$$

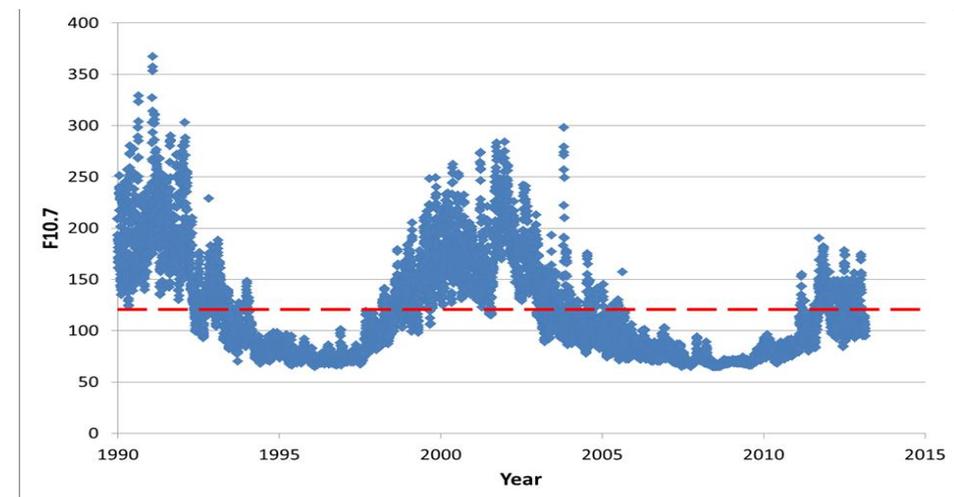
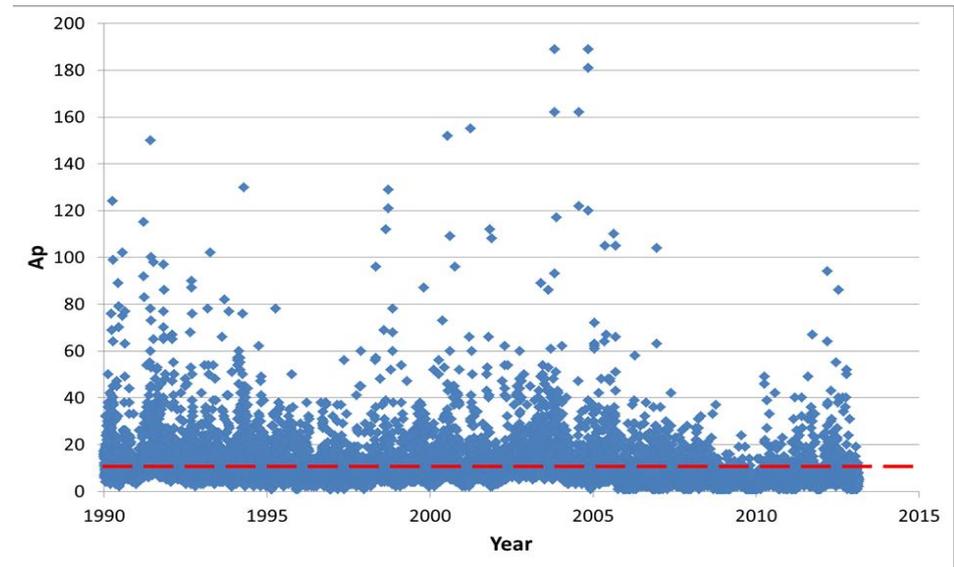
The main driver of satellite drag is
air density

↓
solar activity

For the following computations
an **overestimated average solar activity**
was selected, and **NRLMSIS-00** was used
as atmospheric model.

$$A_p = 11.8$$
$$F_{10.7} = 118.2 \text{E}22 \text{ W/m}^2\text{Hz}$$

For elliptical orbits the drag exponentially
increases with decreasing altitude of the
perigee.

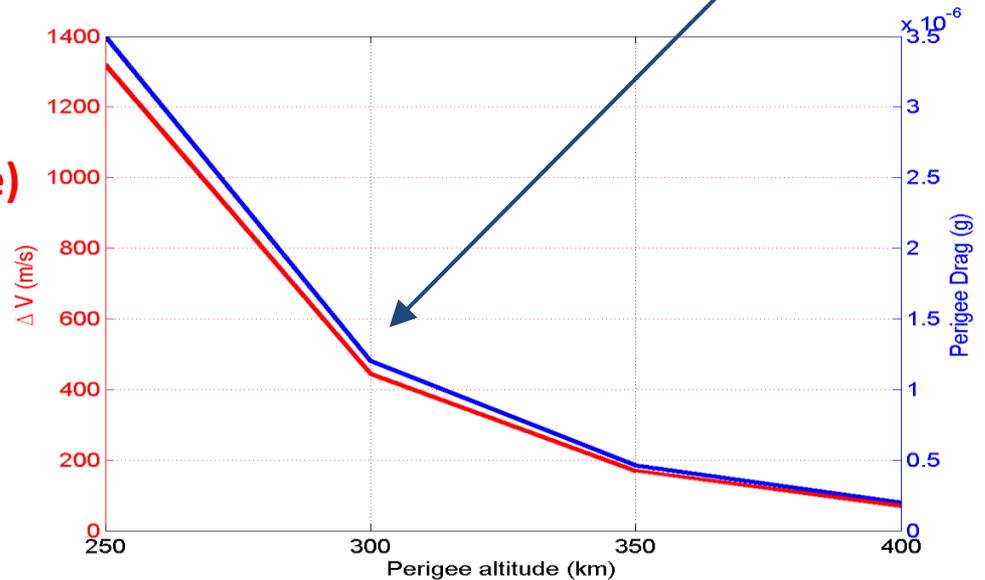


Perigee Determination

h apogee	h perigee	Drag acceleration (maximum value)	Drag ΔV (after 11 years)	m prop (Isp = 300 s)
(km)	(km)	(g)	(m/s)	(kg)
800	400	1.75E-7	80	10
800	350	4.25E-7	185	20
800	300	1.11E-6	480	45
800	250	3.30E-6	1400	150

Selected solution

Total ΔV due to drag is computed to design the orbit (perigee)

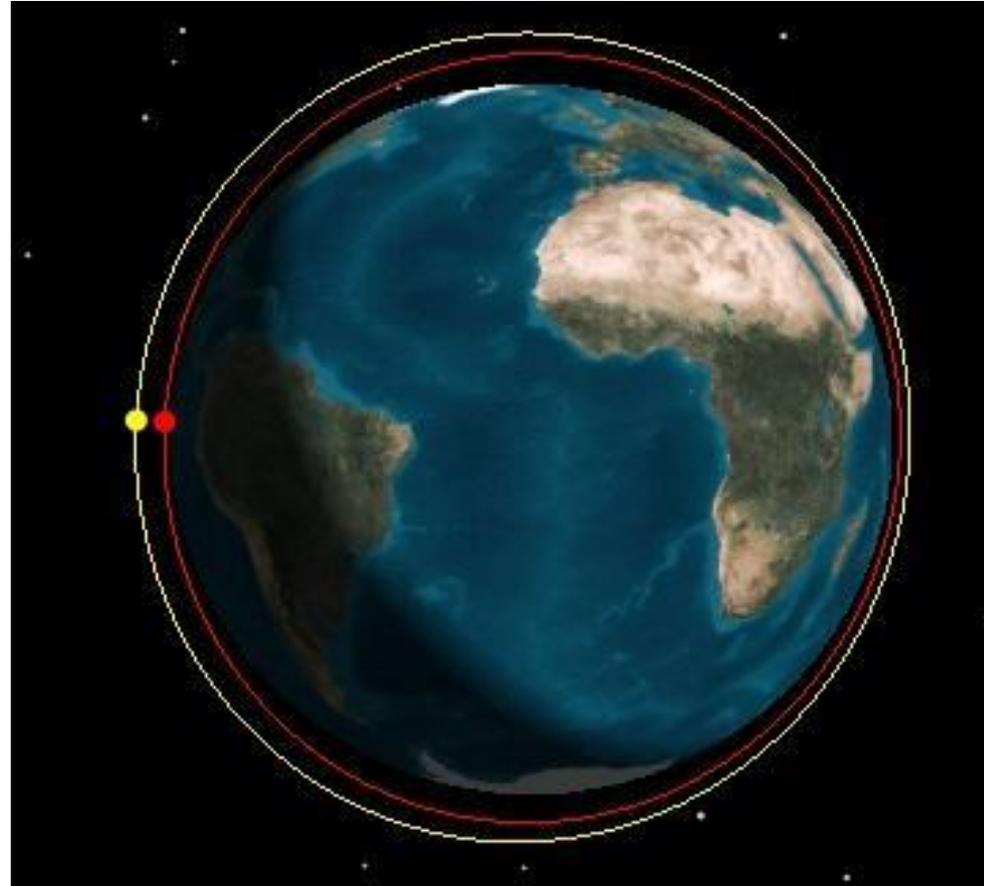


Orbit

Constellation build up:

- Begin with 2 satellites in 800×300 km, 80° inclination orbit.
- A-DONIS: $\Delta V = 0.14$ km/s to make one orbit **circular (800 km)**, with same inclination.
- B-DONIS: $\Delta V = 0.09$ km/s to make one orbit **elliptical (300×500 km)**, with same inclination.

→ provides different precession rates of RAAN

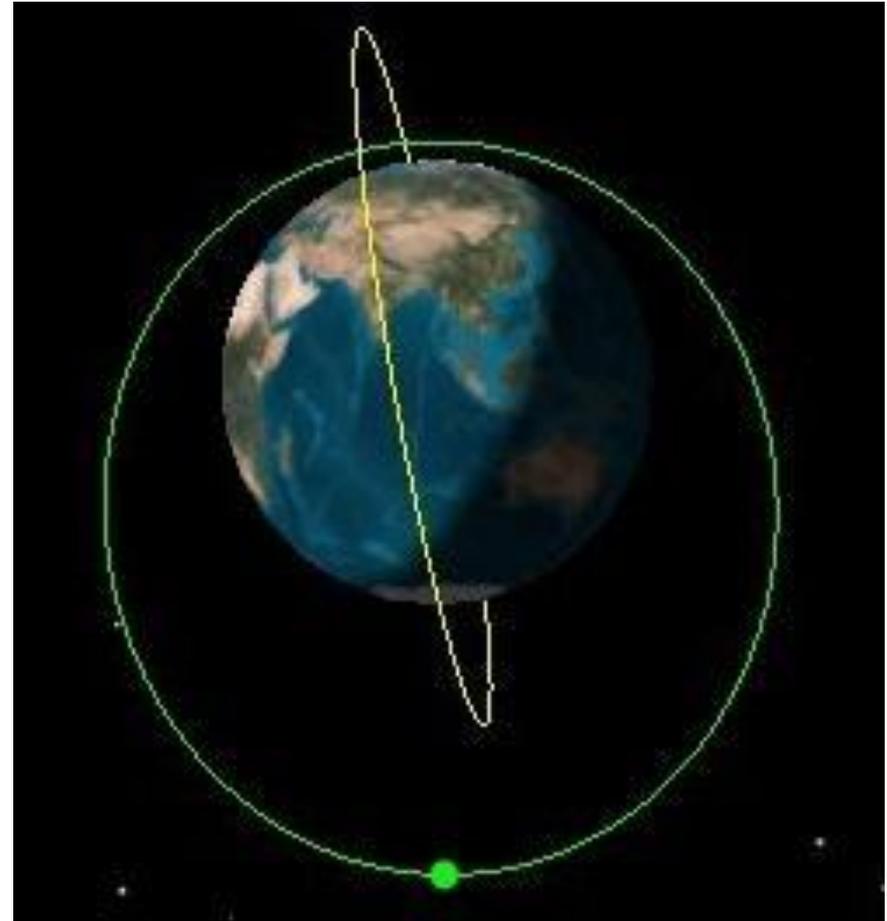


Start constellation



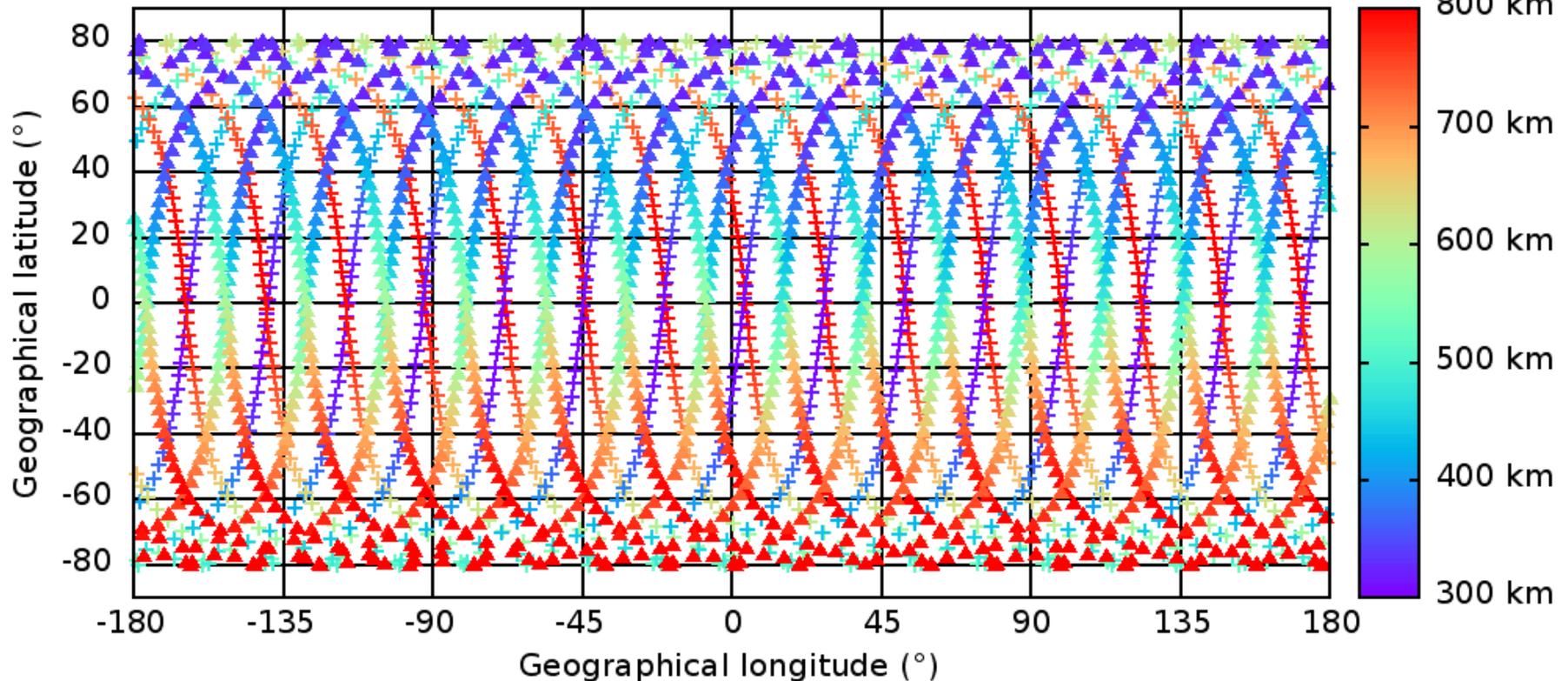
Orbit

- Relative precession rate of ascending node: $0.255^\circ/\text{day}$
- Difference in RAAN becomes equal to 90° (340 days after launch)
→ apply the same ΔV (**apogee kick burn**) to make the two orbits identical, but with **different orbital planes**



Ground Track

A-DONIS and B-DONIS ground track in one day

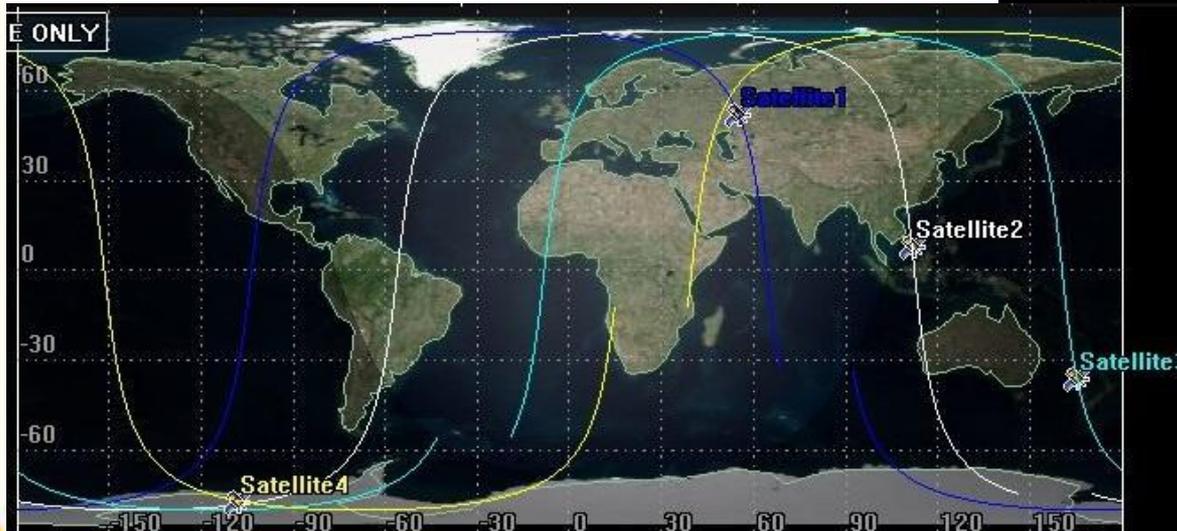


Improvement of spatial sampling via:

- 90° difference in the argument of perigee
- Temporal changes in the orientation of the perigee at same precession rates for both satellites

Orbit

The mission can be expanded by increasing the coverage with two more satellites (45° difference between the planes).



Space Segment

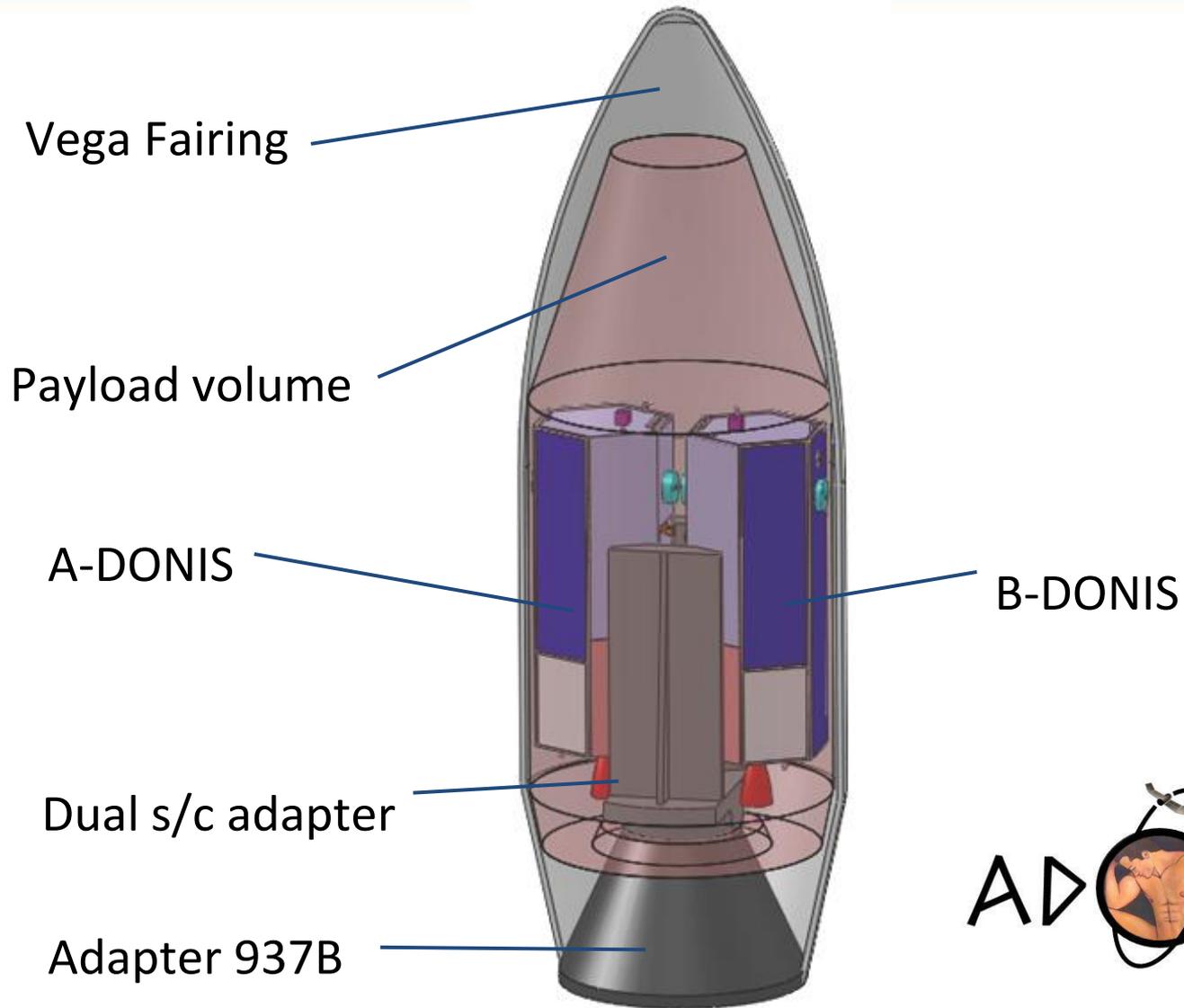
Launcher: Vega

Arianespace Vega

- Cost: **35 M€**
- Liftoff mass: **137 tonnes**
- Payload: **1.5 tonnes** to
800 km altitude
- Mission with **2 s/c**
- Launch site: Guiana
Space Centre, **Kourou**,
French Guiana



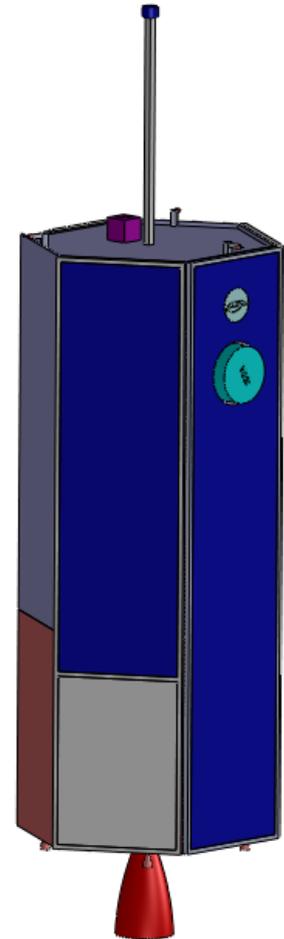
Configuration of S/C in VEGA Fairing



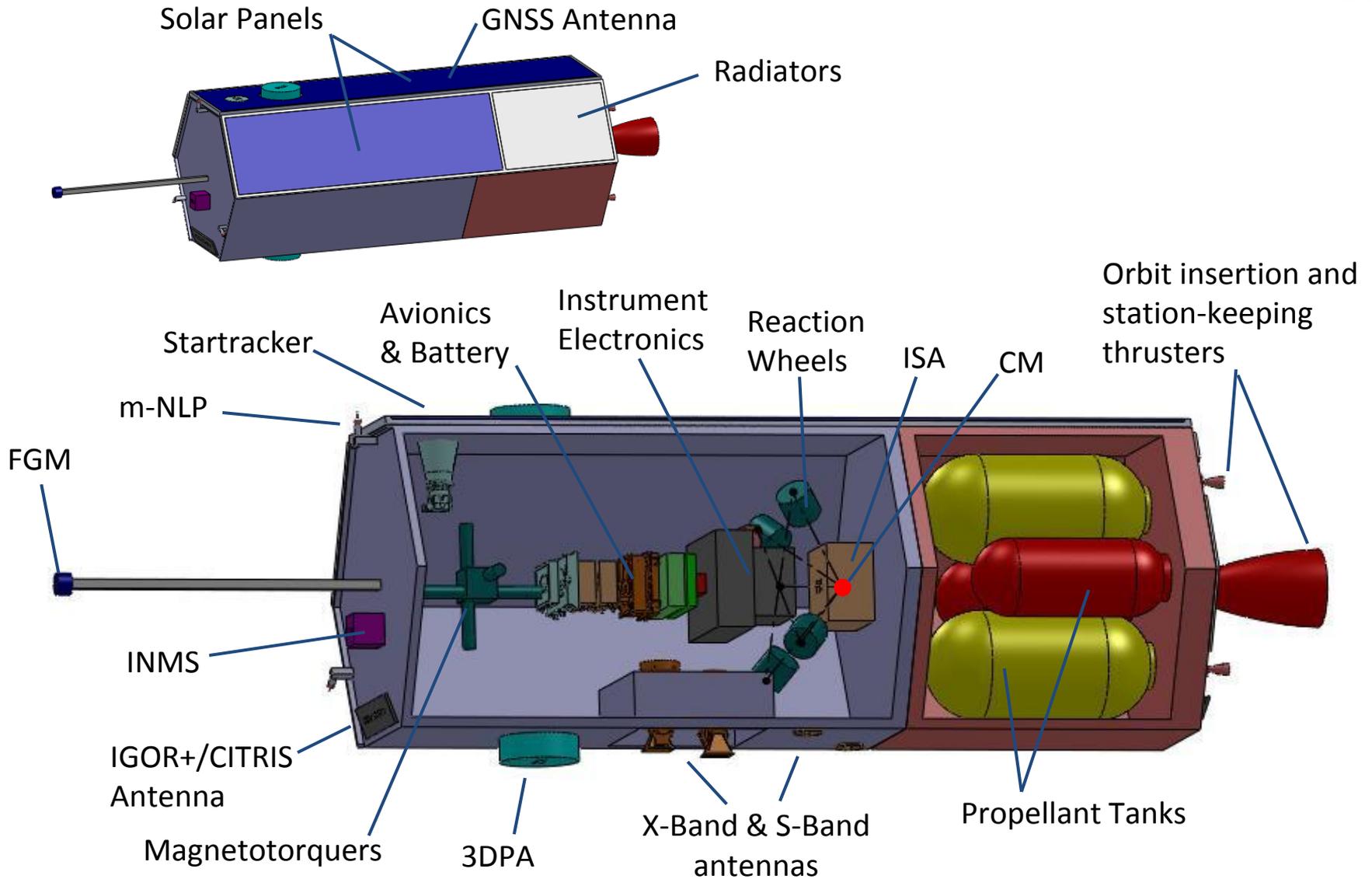
Overview

Based on **commercial Surrey SSTL-300 platform**, customised to meet mission requirements:

- **Small frontal area and simple shape**
- **Propulsion** for orbit insertion and station-keeping
- Increased lifetime for **full solar-cycle** coverage
- **Lightweight structure** to meet payload capacity of Vega launcher

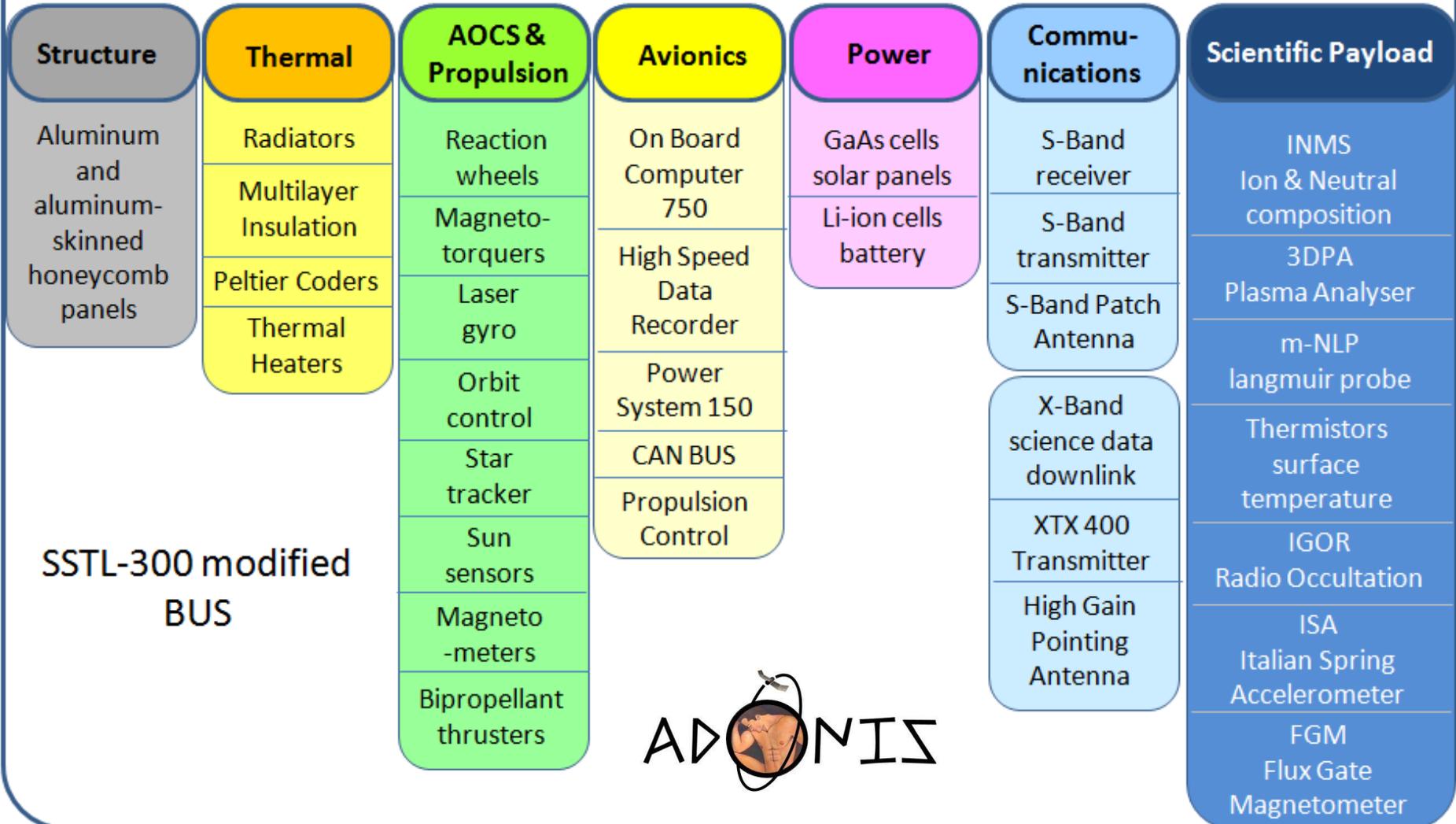


Overview

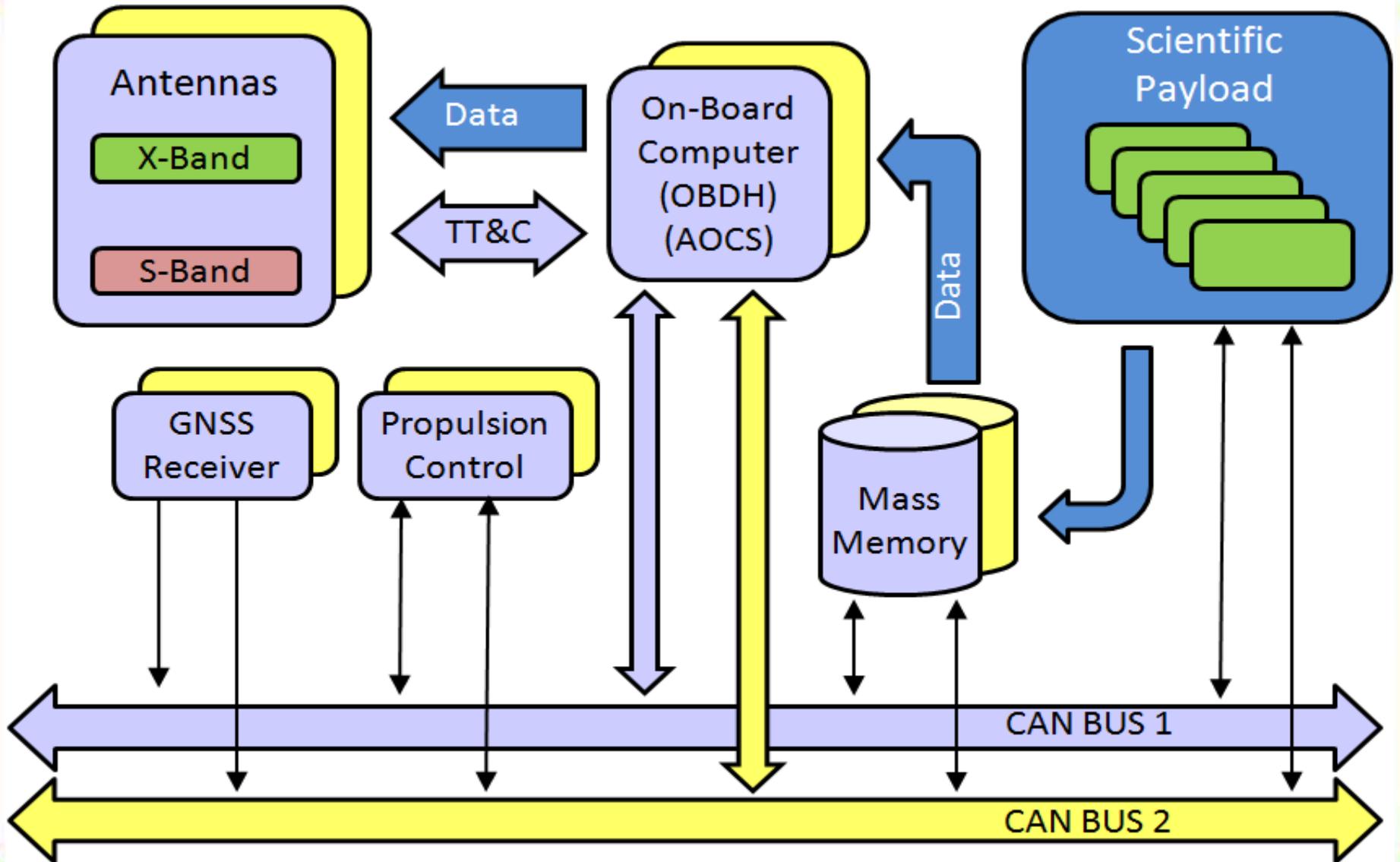


Spacecraft Product Tree

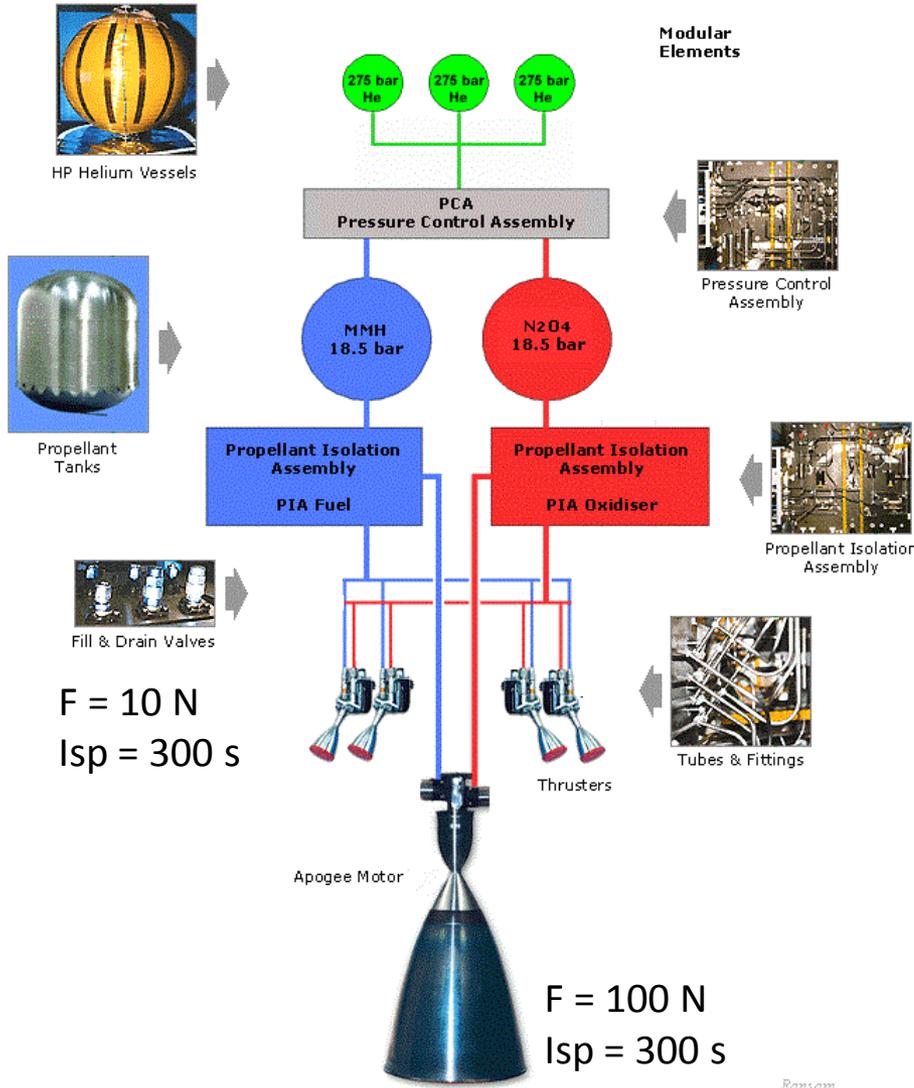
Space Segment



Spacecraft Avionics Architecture



Propulsion System



Maneuver	A-DONIS	B-DONIS
Orbital injection	$\Delta V = 2 \times 140\text{ m/s}$ → 58 kg (25% margin)	$\Delta V = 2 \times 93\text{ m/s}$ → 32 kg (25% margin)
Temporary orbit correction	$\Delta V = 5\text{ m/s}$ → 2 kg (50% margin)	$\Delta V = 100\text{ m/s}$ → 28 kg (25% margin)
Elliptical orbit correction	$\Delta V = 500\text{ m/s}$ → 75 Kg (40% margin)	$\Delta V = 500\text{ m/s}$ → 75 Kg (40% margin)
Avoidance maneuvers	15 kg	15 kg
Sum	150 kg	150 kg

Ransom

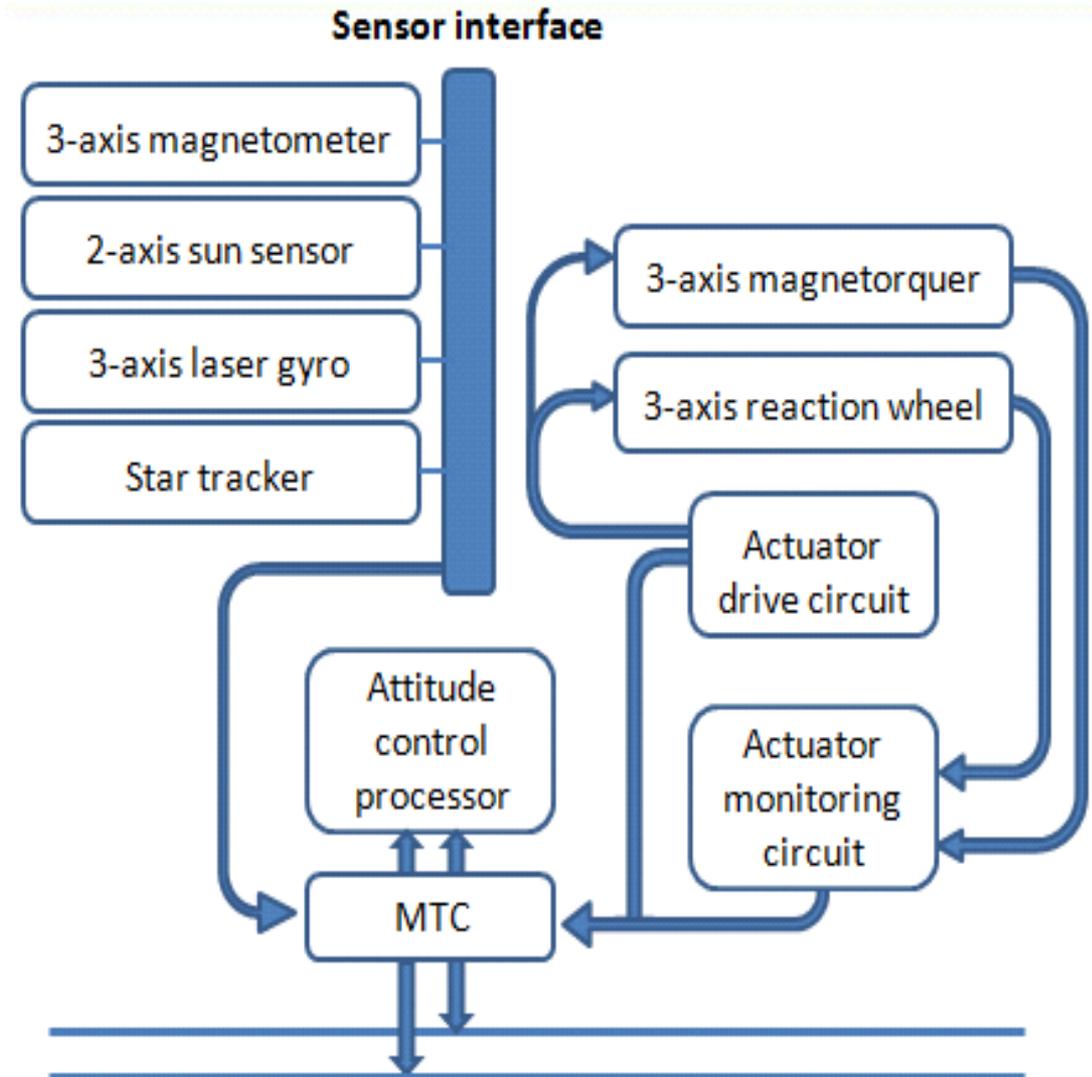
Attitude Control

Attitude control

- Reaction wheels (4 wheels, 0.02 Nm)
- Desaturation with magnetorquers (3 rods, 110 Am²)

Attitude determination

- 2 axis Sun sensors
- 3 axis magnetometers
- Star tracker
- 3 axis gyroscopes (laser gyros)

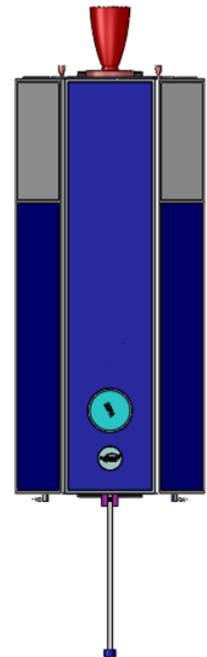


Power

Solar Panels (SP) design: worst case scenario

	Time spent pr. orbit	Power needed
Sunlight	$T_d = 48 \text{ min}$	$P_d = 115 \text{ W}$
No SP exposed to sun	$T_e = 48 \text{ min}$	$P_e = 90 \text{ W}$

$\eta_A = 0.95$ Assembly loss
 $\eta_S = 0.95$ Shadowing loss
 $\eta_T = 0.85$ Temperature loss
 $I_d = \eta_A * \eta_S * \eta_T \cong 0.77$ Inherent degradation



Selected SP cells: (Power Positive)

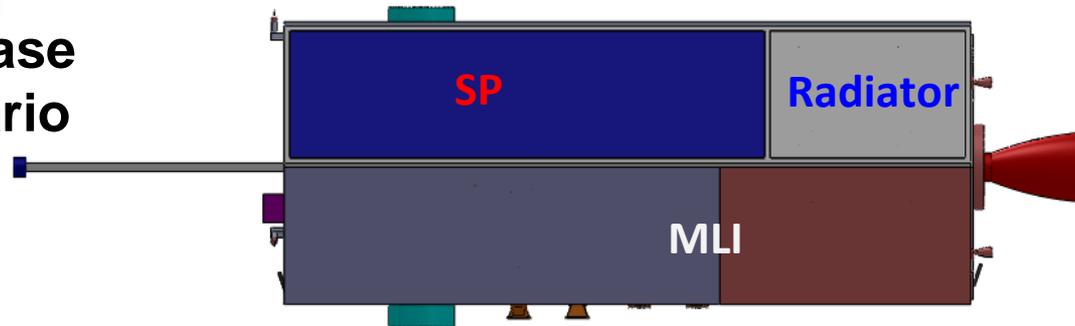
- NeXt Triple Junction (XTJ): $P_0 = 398 \text{ W/m}^2$ $A_{SP} = 2.5 \text{ m}^2$
- GaInP2/GaAs/Ge $\gamma_{deg} = 2.75\% \rightarrow L_d = 0.72$ (after 12 years)

Lithium Ion Batteries: (Power Negative)

- Capacity: 38 Ah Nominal voltage: 3.6 V
- Max. Current : 38 A 1 battery with mass = 950 g (75% discharge)

Thermal

Hot Case Scenario



Passive Thermal control

- **Multilayers Insulation (MLI):** exposed surfaces and underneath Solar Panels.
- **Radiators:** 3 radiators are needed: **2 at the sides** and **1 in the back**.

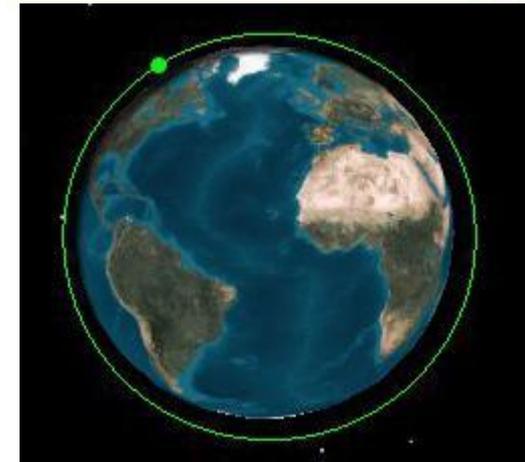
$$P_{BOL-SA} + \alpha S (\Phi_S + \Phi_{E_{alb}}) + \varepsilon S F_{SP} \Phi_{E_{IR}} = n \varepsilon S \sigma T^4$$

$$S_{rad} = 0.4 \text{ m}^2$$

Each radiator will be equipped with louvers. ← The area was selected to optimize the S/C length

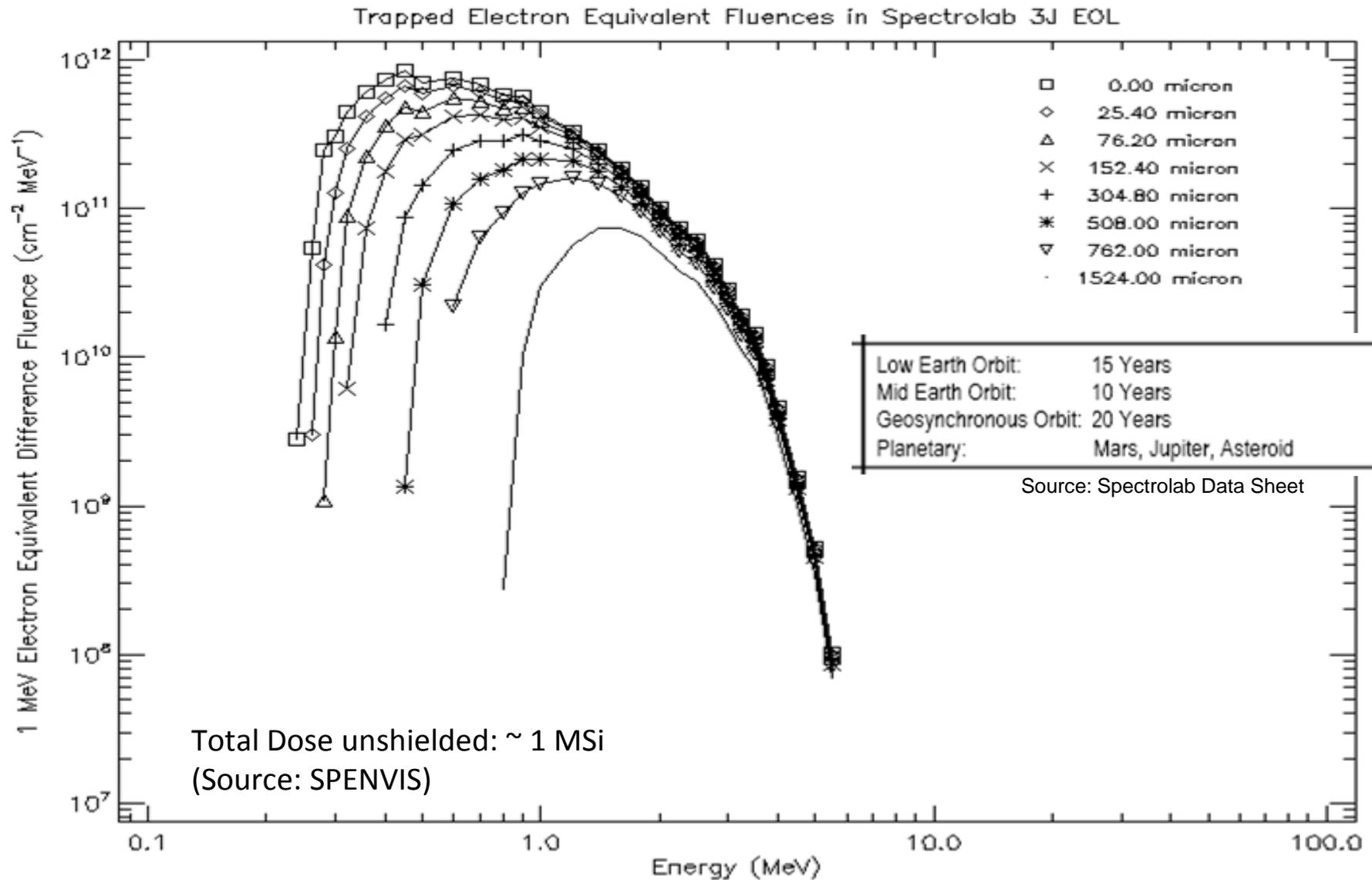
Active Thermal Control

- **Peltier Coolers** will be used to "move" the internal heat toward the radiators.
- **Thermal Heaters** during eclipses.



- P_{BOL-SA} : Power to dissipate $\sim 275 \text{ W}$
- α : Radiator Absorption coefficient ~ 0.1
- S : Radiator area
- Φ_S : Solar flux $\sim 1366 \text{ W/m}^2$
- $\Phi_{E_{alb}}$: Earth flux due to albedo $\sim 239 \text{ W/m}^2$
- $\Phi_{E_{IR}}$: Earth flux due to Infra-Red $\sim 400 \text{ W/m}^2$
- σ : Stephan-Boltzmann constant
- ε : Emissivity ~ 0.8
- F_{SP} : Shape factor ~ 0.4
- n : number of radiations = 3

Radiation Dose and Solar Cell Degradation



Spacecraft Mass Budget

Subsystem	Total (kg)
Structure & Subsystems	325
Avionics & Communications	22
Fuel	165
INMS	3.6
3DPA	1.2
m-NLP	0.3
Boom	3
Thermistors	0.036
CITRIS	5.4
IGOR+	6.96
ISA	9.78
FGM	1.8
TOTAL	545

Mass for launch (kg)	
2 x s/c	1090
Vega capacity	1500
Margin for dual s/c adapter	410

10% margin
20% margin

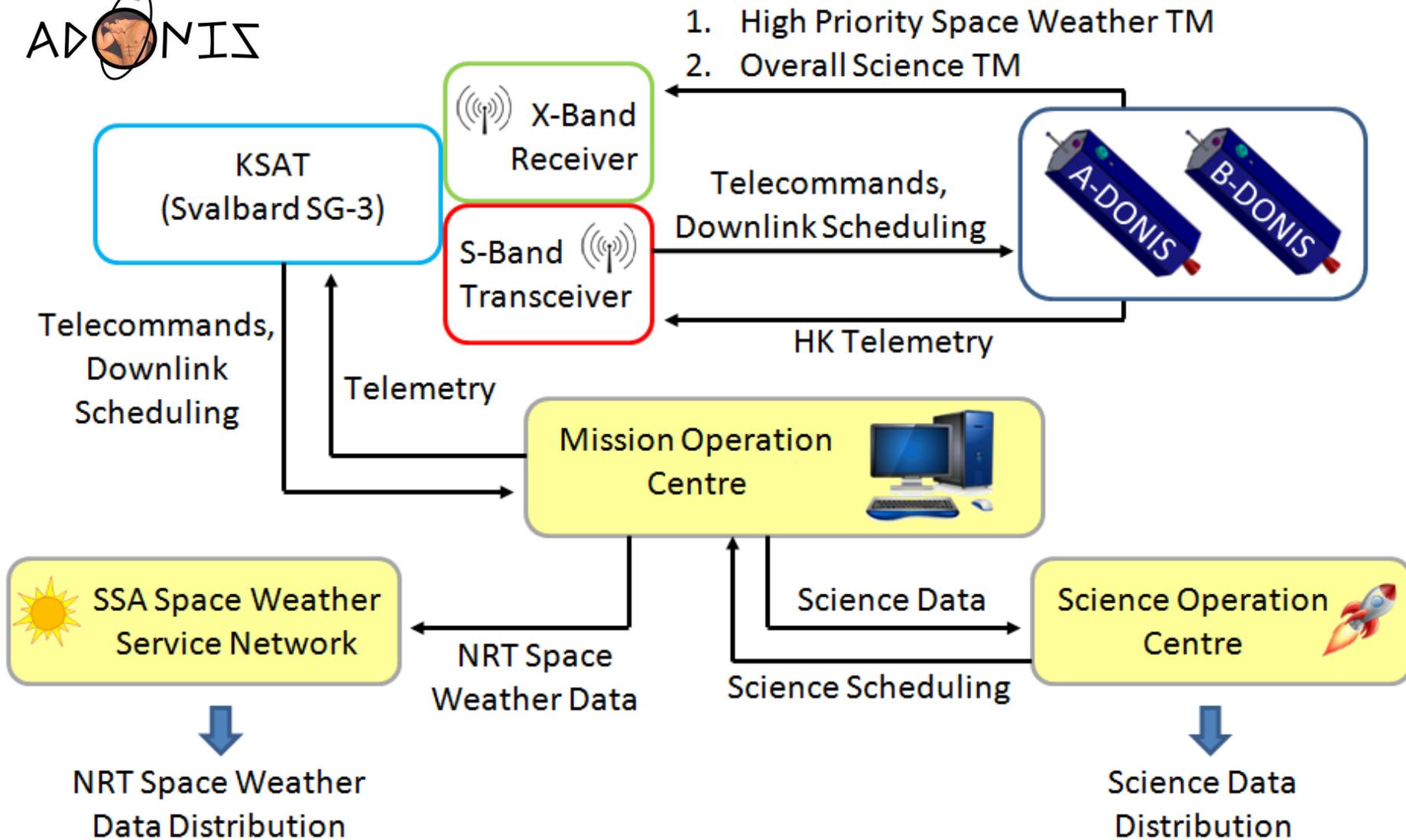
Spacecraft Power and Data Budget

Subsystem	Operation (W)	Data rate (bits/s)
Power provided by Bus	115 (180 peak)	N/A
Avionics	40 (61 peak)	N/A
Communication	15 (50 peak)	N/A
INMS	3	2048
3DPA	1	58000
m-NLP	3.5	1900
Thermistors	0.01	96
CITRIS	12.3	15000
IGOR+	22	20000
ISA	12.1	9600
FGM	0.8	400
TOTAL	110 W (166 W peak)	107 kbps

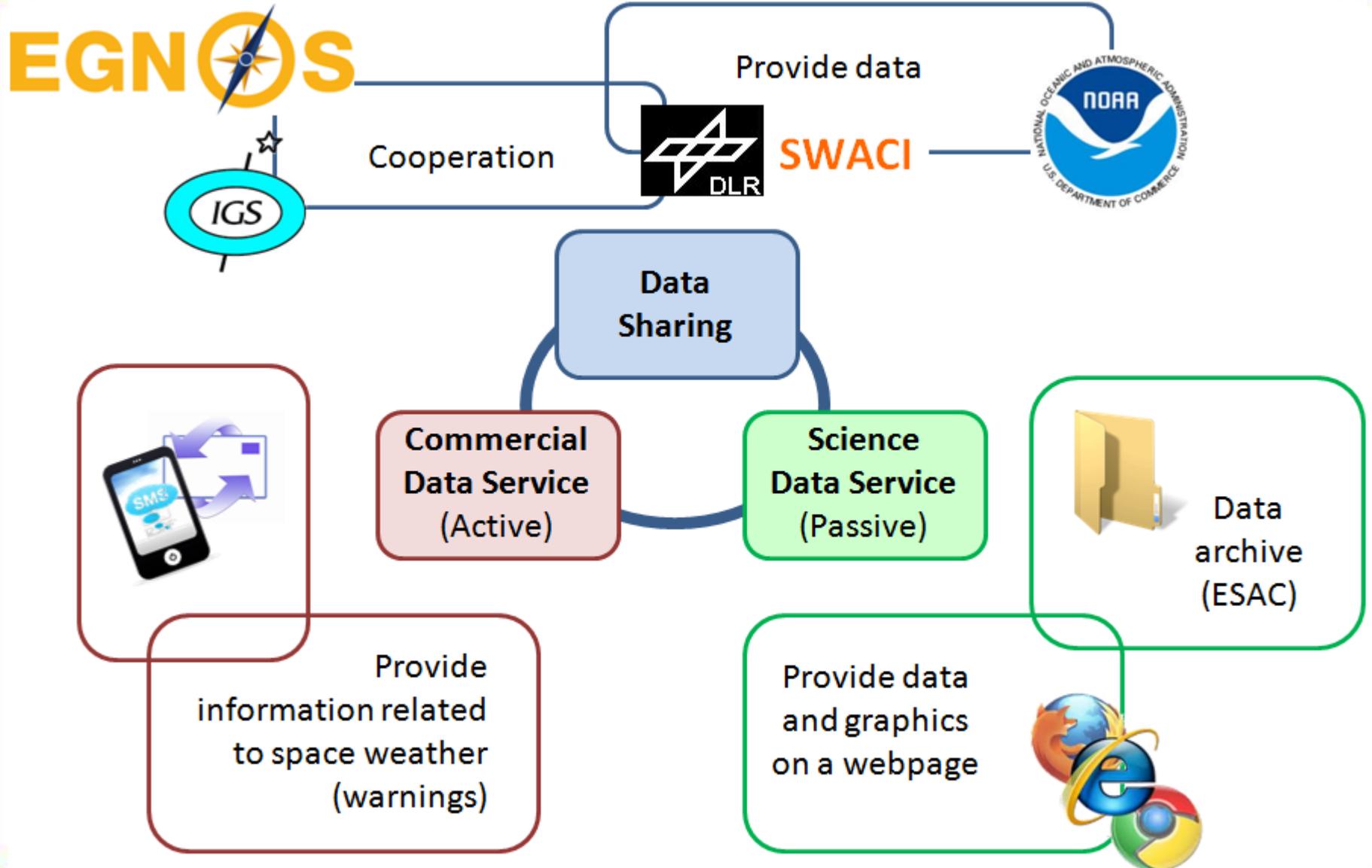


Ground Segment & Operations

Ground Segment & Operations



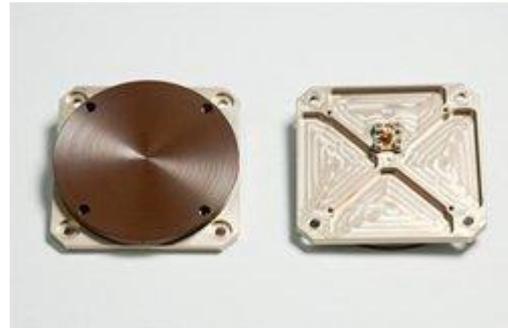
ADONIS Ground Services



Radio Systems Overview

Parameter	X-Band (down)	S-Band (down)	S-Band (up)
Data rate	105 Mbit/s	38.4 kbit/s	19.2 kbit/s
Frequency	8.5 GHz	2.2 GHz	2.1 GHz
Tx Power	5 W	0.5 W	~15W
Tx Antenna	10 cm horn	8 cm patch	13 m dish
Rx Antenna	13 m dish	13 m dish	8 cm patch
Rx G/T	32 dB	23 dB	-25 dB
Link Margin	6.0 dB	15.4 dB	40.6 dB

- Calculated using 2200 km slant range
(Determined from STK simulation)



Ground Coverage I

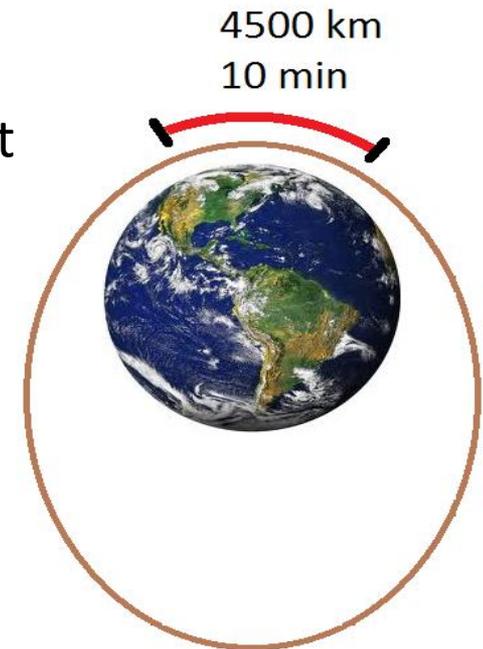
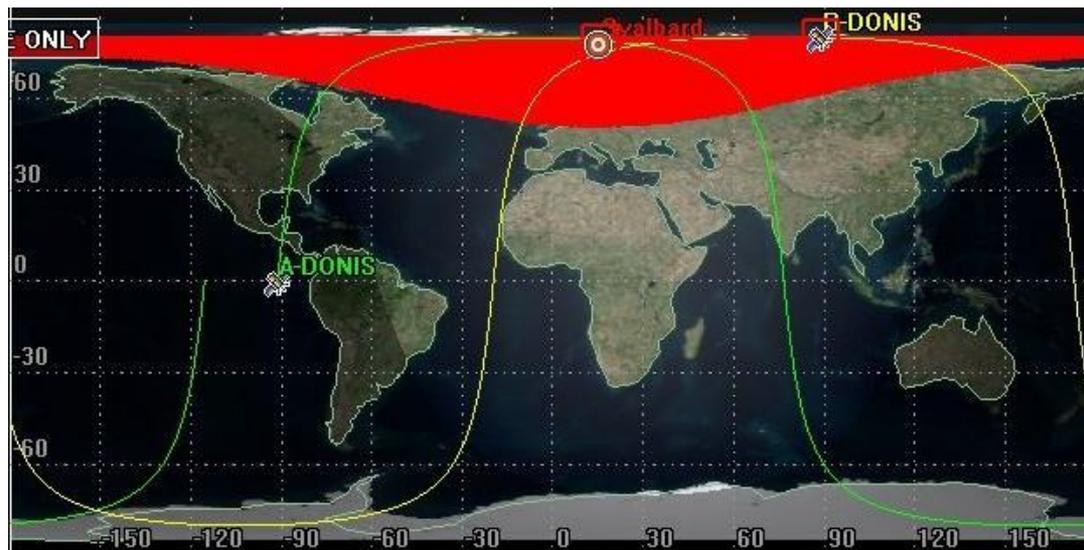
Ground Station (GS) Location: Svalbard (KSAT SG-3)

Orbits with GS coverage: 12.5 of 15.15/day (85%)

Worst-case unusable consecutive passes: 4

- Average ground pass time: 10.5 min/orbit
- Worst-case ground pass time: 4.0 min/orbit

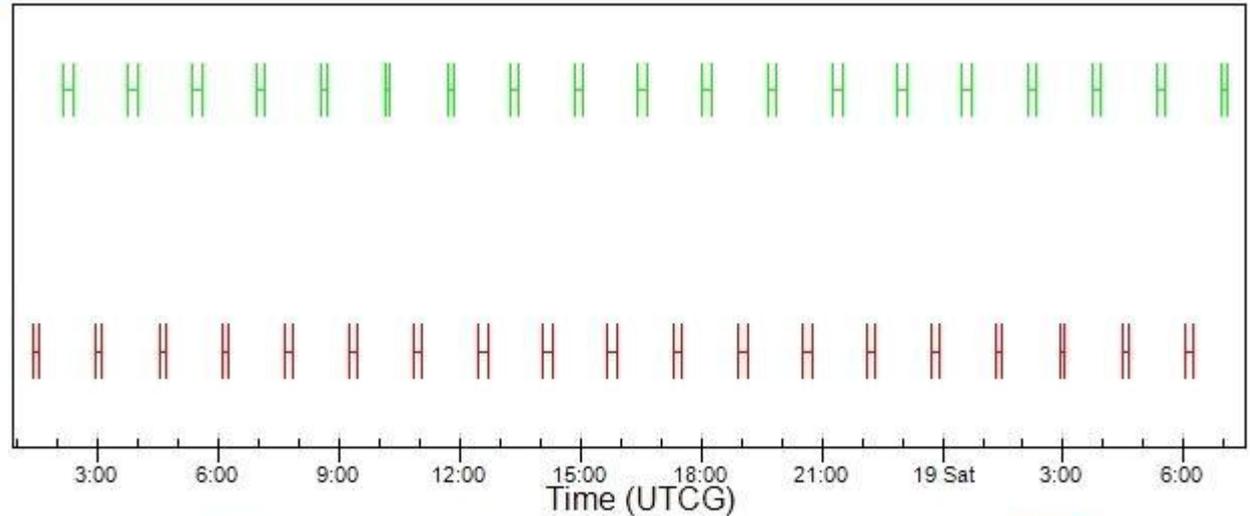
Suggested GS allocation: 4 h/day (for both satellites)



Ground Coverage II

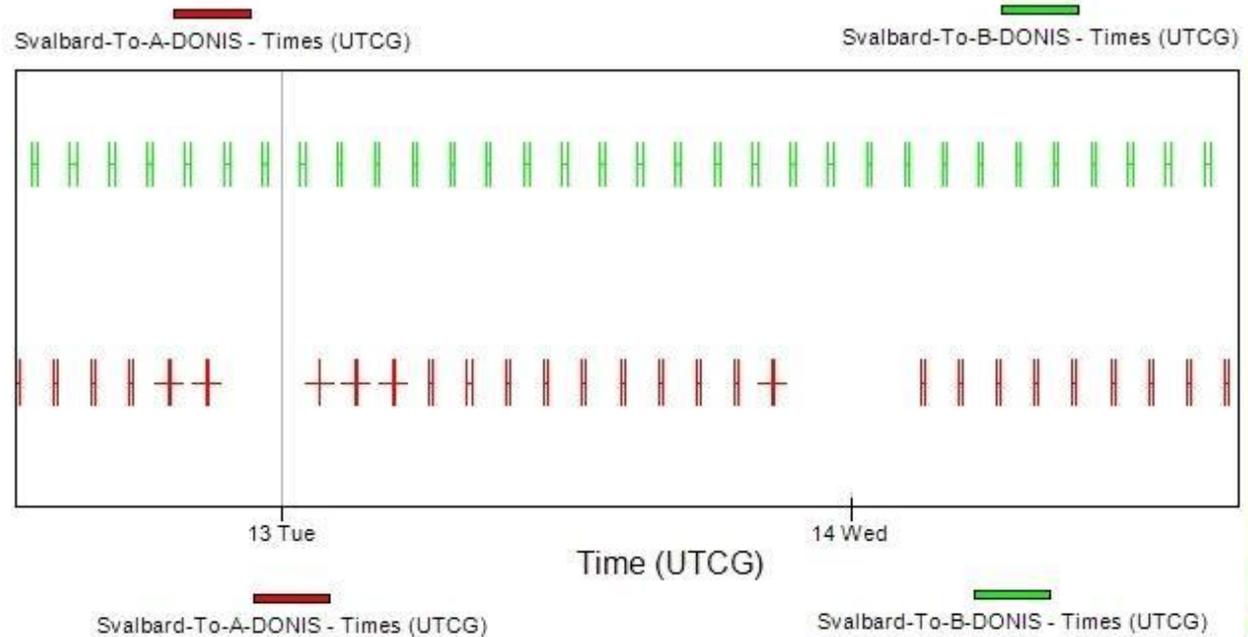
Best case

- ~48 min between downlinks
- >95% of orbits (both satellites)



Worst case

- ~95 min between downlinks
- ~95% for B-DONIS
- ~85% for A-DONIS (alternating)



Science data generation

Parameter	Data generated
Science generated per orbit	720 Mbit
Science generated in 5 orbits (worst-case)	3600 Mbit
Downlink capacity per orbit	4500 Mbit
Worst case data downlink margin	720 Mbit

- Mass memory capacity: 128 Gbit
- Total generated scientific data during mission: 40 Tbit

Development, Costs & Risks

Total Costs

Cost Item	Expected Cost (M€)
Arianespace VEGA launcher	35
2× Spacecraft Standard Platform SSTL	50
Customisation for SSTL	60
2× Propulsion Module	35
2× Total Payload	50
Ground Operations	45
Total	275

Descope Options:

- One spacecraft, less resolution, total descope mission cost: 165 M€
- Shorter mission (5 years), total mission cost: 251 M€

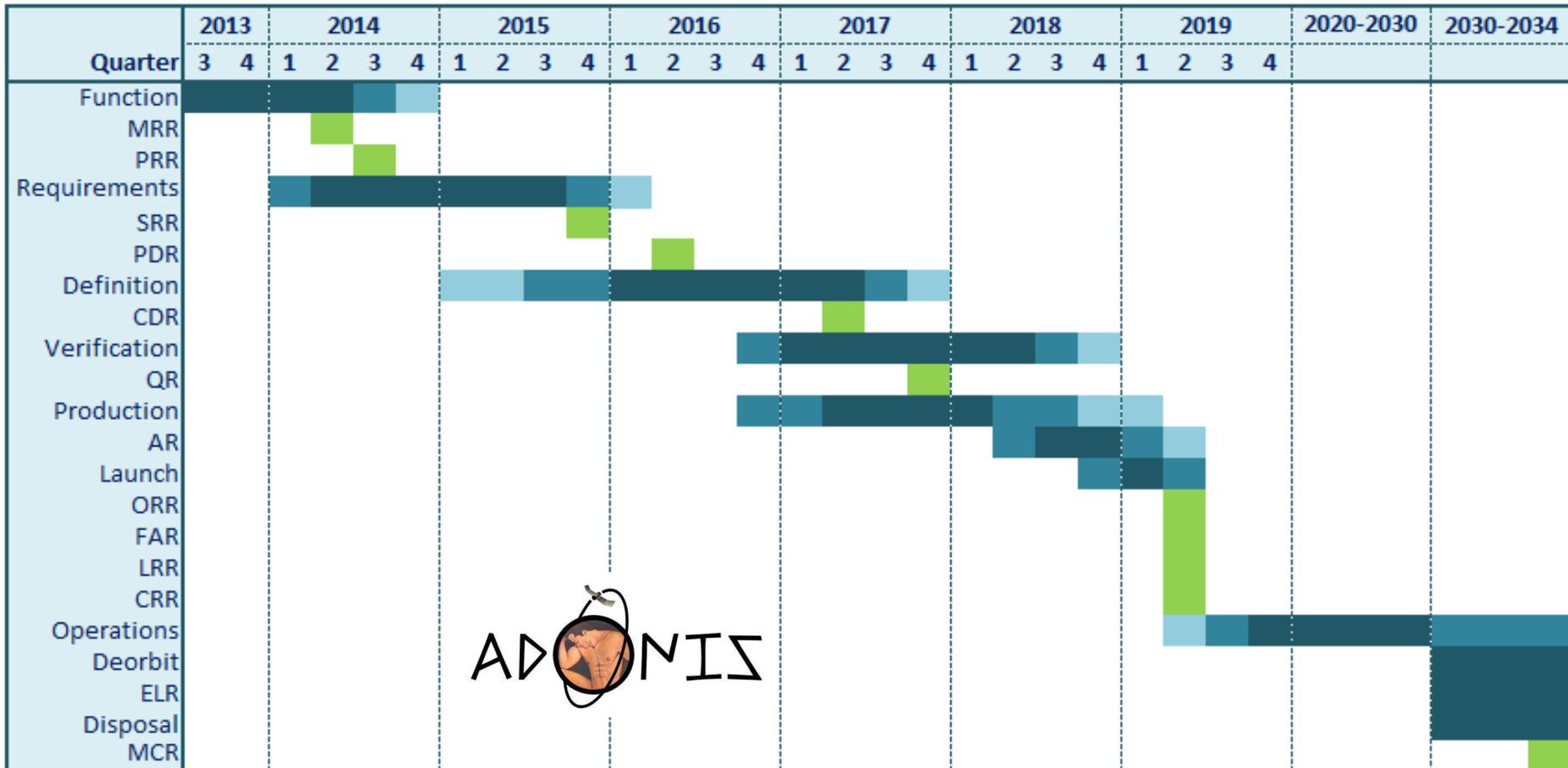
Mission Operations Costs

Parameter	Yearly cost
Satellite tracking	750 k€ / year
Mission Control	2000 k€ / year
Science Operations	1000 k€ / year
NRT Operations	300 k€ / year
Total cost	4050 k€ / year



Total missions operations cost (11 years): 45 M€

Mission Timeline

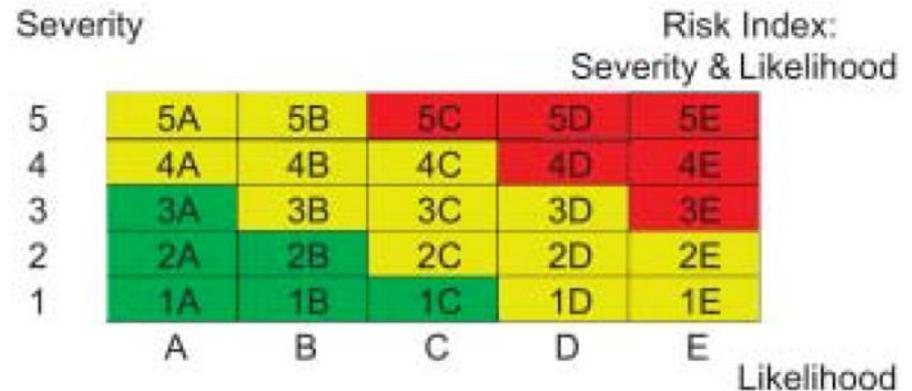


LEGEND			
MDR Mission Design	CDR Critical Design	FAR Flight Acceptance	MCR Mission Close Out
PRR Preliminary Requirements	QR Qualification	LRR Launch Readiness	Milestones
SRR System Requirements	AR Acceptance	CRR Commissioning Result	
PDR Preliminary Design	ORR Operational Readiness	ELR End Of Life	

Risks

Identified risk	Severity	Likelihood	Impact	Mitigation
Launcher failure	5	C	performance	accepted
Plasma analyser not space proven	2	C	performance	replace with existing simpler instrument
Space weather	3	C	performance	accepted
Bus customisation	3	C	cost	replace with different

→ No higher risk than an average Low Earth Orbit mission



P. Falkner, Alpach 2013



Disposal

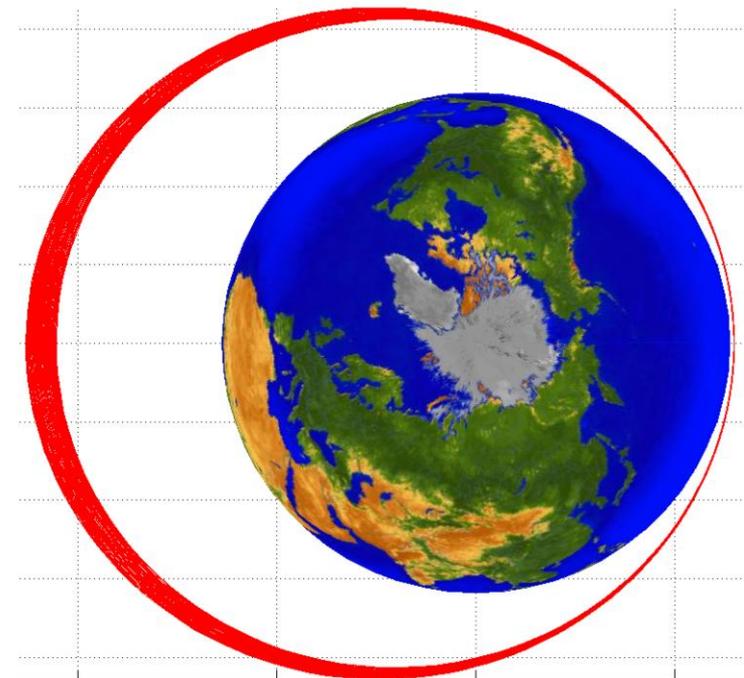
Disposal

ESA requests the removal of space systems in the **LEO region** not later than **25 years after the end of the mission**.



The **orbital decay** will be part of the **scientific phase**, and will allow to:

1. study the drag at **300 km with different perigee velocities** (circularisation phase);
2. study of the drag **below 300 km** until re-entry of the satellites (spiralisation phase);



Disposal Strategy:

Controlled re-entry using thrusters over unpopulated areas as a part of the mission.

Summary

Summary – Novelties – Usages

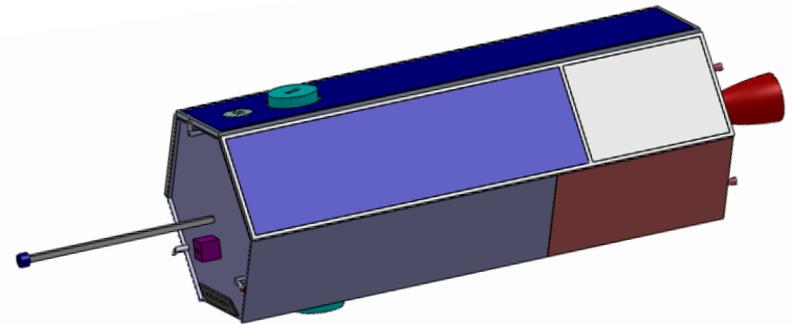
Summary:

- **In-situ** measurement of **drag parameters**
- New altitudes, long duration
- Correlation with SWE
- Data to **improve ionospheric models**
- NRT data near polar regions



Benefits:

- **Launch** optimisation
- **De-orbiting**
- **Fuel** estimates for s/c
- Reduce environmental **pollution** (rerouting polar flights + 30% fuel)
- Optimisation of broadcast **power**
- **TEC map** improvement



Thank you for your attention!

